

Determinants - Row-Reductions - Properties - Inverse Matrices - Volumes

1. Given the following for matrices:

$$\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}, \quad \mathbf{C} = \begin{bmatrix} a & b \\ kc & kd \end{bmatrix}, \quad \mathbf{D} = \begin{bmatrix} a+kc & b+kd \\ c & d \end{bmatrix}.$$

Calculate the determinants of the previous matrices by theorem 2.2.4. In each case, state the row-operation on \mathbf{A} and describe how it effects the determinant.

2. The following questions illustrate some important properties of the determinant.

- (a) The determinant is not, in general, a linear mapping. That is, $\det: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$ is not, in general, such that, $\det(\mathbf{A}+\mathbf{B}) = \det(\mathbf{A})+\det(\mathbf{B})$. The determinant is, in general, *multilinear*.¹ Show this for the domain $\mathbb{R}^{3 \times 3}$ by verifying that $\det(\mathbf{A}) = \det(\mathbf{B}) + \det(\mathbf{C})$, where $\mathbf{A}, \mathbf{B}, \mathbf{C}$ are given as,

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & u_1 + v_1 \\ a_{21} & a_{22} & u_2 + v_2 \\ a_{31} & a_{32} & u_3 + v_3 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} a_{11} & a_{12} & u_1 \\ a_{21} & a_{22} & u_2 \\ a_{31} & a_{32} & u_3 \end{bmatrix}, \quad \mathbf{C} = \begin{bmatrix} a_{11} & a_{12} & v_1 \\ a_{21} & a_{22} & v_2 \\ a_{31} & a_{32} & v_3 \end{bmatrix}.$$

- (b) Show that if \mathbf{A} is invertible, then $\det(\mathbf{A}^{-1}) = \frac{1}{\det(\mathbf{A})}$.
 (c) Let \mathbf{A} and \mathbf{P} be square matrices such that \mathbf{P}^{-1} exists. Show that $\det(\mathbf{PAP}^{-1}) = \det(\mathbf{A})$.
 (d) Let \mathbf{U} be a square matrix such that $\mathbf{U}^T \mathbf{U} = \mathbf{I}$. Show that $\det(\mathbf{U}) = \pm 1$.
 (e) Find a formula for $\det(r\mathbf{A})$ where $\mathbf{A} \in \mathbb{R}^{n \times n}$ and $r \in \mathbb{R}$.

3. Given,

$$\mathbf{A} = \begin{bmatrix} 1 & 5 & -3 \\ 3 & -3 & 3 \\ 2 & 13 & -7 \end{bmatrix}. \tag{1}$$

- (a) Find $\det(\mathbf{A})$ using cofactor expansion.
 (b) Find $\det(\mathbf{A})$ using row reduction to echelon form.

4. Given,

$$\mathbf{A} = \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 2 & 3 & 4 \end{bmatrix}.$$

Calculate the adjugate of \mathbf{A} and using theorem 3.3.8 calculate \mathbf{A}^{-1} .

5. The determinant has a geometric interpretation. In \mathbb{R}^2 , $\det(\mathbf{A})$ is the area of the parallelogram formed by the two vectors $\mathbf{a}_1, \mathbf{a}_2$, where $\mathbf{A} = [\mathbf{a}_1 \ \mathbf{a}_2]$. In \mathbb{R}^3 , $\det(\mathbf{A})$ is the volume of the parallelepiped formed by the three vectors $\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3$, where $\mathbf{A} = [\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3]$.

Using the concept of volume, explain why the determinant of a 3×3 matrix \mathbf{A} is zero if and only if \mathbf{A} is not invertible.

Note: No credit will be given for the use of Theorem 3.2.4. Also, note that there are two proofs here. The forward proof should assume that $\det(\mathbf{A})=0$ and conclude that \mathbf{A} is singular by using the geometry formed by the column vectors. The backward proof should start assuming \mathbf{A} is singular and conclude that the parallelepiped volume is zero. The two proofs together prove the *if and only if* statement above.

Hint: Use the invertible matrix theorem of 2.3 and a geometric description of linearly dependent vectors in \mathbb{R}^3 .

¹A multilinear map is a mathematical function of several vector variables that is linear in each variable. That is, if all columns except one are fixed, then the determinant is a linear function of that one column. See http://en.wikipedia.org/wiki/Multilinear_map for more information.

Homework 5 - Solutions

1. i. $\det(A) = ad - bc$

ii. $\det(B) = cb - ad = -(ad - bc) = -\det(A)$

iii. $\det(D) = d(a+kc) - e(b+kd) = ad + kdc - cb - ed \cdot k =$
 $= ad - bc = \det(A)$
Note. ↑
I switched

iv. $\det(C) = ad \cdot k - kc \cdot b = k(ad - bc) = k \det(A)$

$A \sim B$ by a row interchange and ii. shows $\det(A) = -\det(B)$

$A \sim C$ by a Row Scaling and iv. shows $\det(B) = k \det(A)$

$A \sim D$ by a Row interchange where a multiple of 1 row is added to another. iii. shows that $\det(A) = \det(D)$.

2. a. Elementary matrices E_5, E_6 corresponds to Row interchanges.

$$\det(E_5) = -1 \cdot \det \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = (-1) \cdot 1 = -1$$

$$\det(E_6) = 1 \cdot \det \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = -1$$

The determinant of a ^{Elementary} Row Interchange matrix is -1.

b. Elementary matrices E_3, E_4 correspond to Row scaling.

$$\det(E_3) = k \cdot 1 \cdot 1 = k \quad \text{by diagonal matrix theorem.}$$

$$\det(E_4) = 1 \cdot k \cdot 1 = k$$

The determinant of a ^{Elementary} Row scaling by k is k .

c. Elementary matrices E_1, E_2 correspond to Row Replacements.

$$\det(E_1) = 1 \cdot \det \begin{pmatrix} 1 & 0 \\ k & 1 \end{pmatrix} = 1 \cdot (1 - 0) = 1$$

$$\det(E_2) = 1 \cdot \det \begin{pmatrix} 1 & 0 \\ r & 1 \end{pmatrix} = 1$$

The determinant of an elementary Row Replacement is 1.

Homework 6 - Solutions

1.

a.

$$(1) \quad \det(A) = a_{11} \cdot \det \begin{pmatrix} a_{22} & u_2 + v_2 \\ a_{32} & u_3 + v_3 \end{pmatrix} - a_{12} \det \begin{pmatrix} a_{21} & u_2 + v_2 \\ a_{31} & u_3 + v_3 \end{pmatrix} + (u_1 + v_1) \det \begin{pmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{pmatrix}$$

$$(2) \quad \det(B) = a_{11} \det \begin{pmatrix} a_{22} & u_2 \\ a_{32} & u_3 \end{pmatrix} + -a_{12} \det \begin{pmatrix} a_{21} & u_2 \\ a_{31} & u_3 \end{pmatrix} + u_1 \cdot \det \begin{pmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{pmatrix}$$

$$(3) \quad \det(C) = a_{11} \cdot \det \begin{pmatrix} a_{22} & v_2 \\ a_{32} & v_3 \end{pmatrix} - a_{12} \det \begin{pmatrix} a_{21} & v_2 \\ a_{31} & v_3 \end{pmatrix} + v_1 \cdot \det \begin{pmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{pmatrix}$$

Since,

$$(4) \quad a_{11} \left\{ \det \begin{pmatrix} a_{22} & u_2 \\ a_{32} & u_3 \end{pmatrix} + \det \begin{pmatrix} a_{22} & v_2 \\ a_{32} & v_3 \end{pmatrix} \right\} = a_{11} \left\{ a_{22} u_3 - a_{32} u_2 + a_{22} v_3 - a_{32} v_2 \right\}$$

$$(5) \quad a_{11} \det \begin{pmatrix} a_{22} & u_2 + v_2 \\ a_{32} & u_3 + v_3 \end{pmatrix} = a_{11} \cdot \left\{ a_{22}(u_3 + v_3) - a_{32}(u_2 + v_2) \right\}$$

$$(6) \quad -a_{12} \left\{ \det \begin{pmatrix} a_{21} & u_2 \\ a_{31} & u_3 \end{pmatrix} + \det \begin{pmatrix} a_{21} & v_2 \\ a_{31} & v_3 \end{pmatrix} \right\} = -a_{12} \cdot \left\{ a_{21} u_3 - a_{31} u_2 + a_{21} v_3 - a_{31} v_2 \right\}$$

$$(7) \quad -a_{12} \det \begin{pmatrix} a_{21} & v_2 + u_2 \\ a_{31} & u_3 + v_3 \end{pmatrix} = -a_{12} \left\{ a_{21}(u_3 + v_3) - a_{31}(v_2 + u_2) \right\}$$

$$(4) = (5), \quad (6) = (7) \Rightarrow \det(A) = \det(B) + \det(C).$$

$$b. \det(AA^{-1}) = \det(A) \cdot \det(A^{-1}) = \det(I) \Leftrightarrow \text{(By theorem)}$$

$$\Leftrightarrow \det(A) \cdot \det(A^{-1}) = 1 \Leftrightarrow \text{(By theorem)}$$

$$\Leftrightarrow \det(A^{-1}) = \frac{1}{\det(A)}$$

□

$$c. \det(PAP^{-1}) = \det(P) \cdot \det(A) \cdot \det(P^{-1}) = \text{(By theorem)}$$

$$= \det(P) \cdot \frac{1}{\det(P)} \cdot \det(A) = \det(A) \quad \text{(By commutativity of scalars + Part b.)}$$

$$d. \det(U^T U) = \det(U^T) \det(U) = \text{(By theorem)}$$

$$= (\det(U))^2 = \det(I) = 1 \Leftrightarrow$$

$$\Leftrightarrow \sqrt{(\det(U))^2} = \pm \det(U) = 1 \Rightarrow \det(U) = \pm 1 \quad \square$$

e) If $A \in \mathbb{R}^{n \times n}$ then ΓA is a matrix that has n -many row scalings

$$\det(\Gamma A) = \det(A) = \Gamma^n \det(A)$$

$$2. \det(A) = \begin{vmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 2 & 3 & 4 \end{vmatrix} = \begin{vmatrix} 3 & 0 & 4 \\ 0 & 2 & 1 \\ 2 & 3 & 4 \end{vmatrix} = \begin{vmatrix} 3 & 0 & 4 \\ 0 & 2 & 1 \\ 2 & 0 & 5/2 \end{vmatrix} =$$

$$= 2 \cdot \det \begin{pmatrix} 3 & 4 \\ 2 & 5/2 \end{pmatrix} = 2 \cdot \left\{ \frac{3 \cdot 5}{2} - 2 \cdot 4 \right\} = 2 \cdot (-1/2) = -1$$

$$\text{adj } A = \begin{bmatrix} C_{11} & C_{21} & C_{31} \\ C_{12} & C_{22} & C_{32} \\ C_{13} & C_{23} & C_{33} \end{bmatrix}$$

where

$$C_{11} = \begin{vmatrix} 2 & 1 \\ 3 & 4 \end{vmatrix} = 8 - 3 = 5, \quad C_{21} = -\begin{vmatrix} 6 & 7 \\ 3 & 4 \end{vmatrix} = -(24 - 21) = -3, \quad C_{31} = \begin{vmatrix} 6 & 7 \\ 2 & 1 \end{vmatrix} = 6 - 14 = -8$$

$$C_{12} = -\begin{vmatrix} 0 & 1 \\ 2 & 4 \end{vmatrix} = +2, \quad C_{22} = \begin{vmatrix} 3 & 7 \\ 2 & 4 \end{vmatrix} = 12 - 14 = -2, \quad C_{32} = -\begin{vmatrix} 3 & 7 \\ 0 & 1 \end{vmatrix} = -3$$

$$C_{13} = \begin{vmatrix} 0 & 2 \\ 2 & 3 \end{vmatrix} = -4, \quad C_{23} = -\begin{vmatrix} 3 & 6 \\ 2 & 3 \end{vmatrix} = -(9 - 12) = 3, \quad C_{33} = \begin{vmatrix} 3 & 6 \\ 0 & 2 \end{vmatrix} = 6 - 0 = 6$$

Using theorem 3.38 we have that

$$A^{-1} = \frac{1}{\det(A)} \cdot \text{adj}(A) = -1 \cdot \begin{bmatrix} 5 & -3 & -8 \\ 2 & -2 & -3 \\ -4 & 3 & 6 \end{bmatrix} = \begin{bmatrix} -5 & 3 & 8 \\ -2 & 2 & 3 \\ 4 & -3 & -6 \end{bmatrix} = A^{-1}$$

$$3) \textcircled{a} \det(A) = 1 \cdot \det \begin{pmatrix} -3 & 3 \\ 13 & -7 \end{pmatrix} - 5 \det \begin{pmatrix} 3 & 3 \\ 2 & -7 \end{pmatrix} + -3 \det \begin{pmatrix} 3 & -3 \\ 2 & 13 \end{pmatrix} =$$

$$= -18 - 5 \cdot -27 - 3 \cdot 45 = -18$$

$$b) \begin{vmatrix} 1 & 5 & -3 \\ 3 & -3 & 3 \\ 2 & 13 & -7 \end{vmatrix} = \begin{vmatrix} 1 & 5 & -3 \\ 0 & -18 & 12 \\ 0 & 3 & -1 \end{vmatrix} =$$

$$= +6 \begin{vmatrix} 1 & 5 & -3 \\ 0 & -3 & 2 \\ 0 & +3 & -1 \end{vmatrix} = 6 \begin{vmatrix} 1 & 5 & -3 \\ 0 & -3 & 2 \\ 0 & 0 & 1 \end{vmatrix} = 6 \cdot -3 = -18$$

5.

Forward direction-

Assume $A_{3 \times 3}$ is such that $\det(A) = 0$. Then the volume of the parallelepiped spanned by $\vec{a}_1, \vec{a}_2, \vec{a}_3$ has zero volume. That is, the parallelepiped does not exist. This implies that all the vectors $\vec{a}_1, \vec{a}_2, \vec{a}_3$ lie in the same plane, and form a linearly dependent set. Thus, by the invertible matrix theorem A^{-1} does not exist.

Backward direction:

Assume A is ^{not} invertible. Then the columns of A are linearly dependent and $\text{span}\{\vec{a}_1, \vec{a}_2, \vec{a}_3\}$ is at most (in terms of dimension) a plane which has zero volume and cannot form a parallelepiped. Thus, $\det(A) = 0$.