# Vector Spaces <br> Section 4.3: Coordinate Systems 

pgs. 246-256
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## Lecture: Coordinate Systems

Unique Representation Theorem
Topics: Definition of Coordinates
Coordinate mappings

Problems
Prac: 1, 2
Prob: 3, 7, 13, 15, 16, 17, 27, 31

## Section Goals

- Understand how complete bases specify unique representations of vectors from the spaces they span in terms of weights of linear combinations of basis vectors.
- Study the representation of vectors under different bases using the concept of coordinate transformation and from this extrapolate the concept of information equivalence relative to coordinate systems.


## Section Objectives

- State the unique representation theorem and its associated vocabulary of coordinates relative to bases.
- Provide an example of coordinate transformation and representation of vectors under different bases of $\mathbb{R}^{2}$.
- Present an example using the standard polynomial basis highlighting its structural equivalence to $\mathbb{R}^{n+1}$.

