

**6-3.** The element of distance in three-dimensional space is

$$dS = \sqrt{dx^2 + dy^2 + dz^2} \quad (1)$$

Suppose  $x, y, z$  depends on the parameter  $t$  and that the end points are expressed by  $(x_1(t_1), y_1(t_1), z_1(t_1)), (x_2(t_2), y_2(t_2), z_2(t_2))$ . Then the total distance is

$$S = \int_{t_1}^{t_2} \sqrt{\left[\frac{dx}{dt}\right]^2 + \left[\frac{dy}{dt}\right]^2 + \left[\frac{dz}{dt}\right]^2} dt \quad (2)$$

The function  $f$  is identified as

$$f = \sqrt{\dot{x}^2 + \dot{y}^2 + \dot{z}^2} \quad (3)$$

Since  $\frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} = \frac{\partial f}{\partial z} = 0$ , the Euler equations become

$$\left. \begin{aligned} \frac{d}{dt} \frac{\partial f}{\partial \dot{x}} &= 0 \\ \frac{d}{dt} \frac{\partial f}{\partial \dot{y}} &= 0 \\ \frac{d}{dt} \frac{\partial f}{\partial \dot{z}} &= 0 \end{aligned} \right\} \quad (4)$$

from which we have

$$\left. \begin{aligned} \frac{\dot{x}}{\sqrt{\dot{x}^2 + \dot{y}^2 + \dot{z}^2}} &= \text{constant} \equiv C_1 \\ \frac{\dot{y}}{\sqrt{\dot{x}^2 + \dot{y}^2 + \dot{z}^2}} &= \text{constant} \equiv C_2 \\ \frac{\dot{z}}{\sqrt{\dot{x}^2 + \dot{y}^2 + \dot{z}^2}} &= \text{constant} \equiv C_3 \end{aligned} \right\} \quad (5)$$

From the combination of these equations, we have

$$\left. \begin{aligned} \frac{\dot{x}}{C_1} &= \frac{\dot{y}}{C_2} \\ \frac{\dot{y}}{C_2} &= \frac{\dot{z}}{C_3} \end{aligned} \right\} \quad (6)$$

If we integrate (6) from  $t_1$  to the arbitrary  $t$ , we have

$$\left. \begin{aligned} \frac{x-x_1}{C_1} &= \frac{y-y_1}{C_2} \\ \frac{y-y_1}{C_2} &= \frac{z-z_1}{C_3} \end{aligned} \right] \quad (7)$$

On the other hand, the integration of (6) from  $t_1$  to  $t_2$  gives

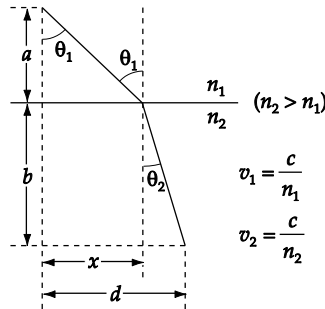
$$\left. \begin{aligned} \frac{x_2-x_1}{C_1} &= \frac{y_2-y_1}{C_2} \\ \frac{y_2-y_1}{C_2} &= \frac{z_2-z_1}{C_3} \end{aligned} \right] \quad (8)$$

from which we find the constants  $C_1$ ,  $C_2$ , and  $C_3$ . Substituting these constants into (7), we find

$$\boxed{\frac{x-x_1}{x_2-x_1} = \frac{y-y_1}{y_2-y_1} = \frac{z-z_1}{z_2-z_1}} \quad (9)$$

This is the equation expressing a straight line in three-dimensional space passing through the two points  $(x_1, y_1, z_1)$ ,  $(x_2, y_2, z_2)$ .

### 6-7.



The time to travel the path shown is (cf. Example 6.2)

$$t = \int \frac{ds}{v} = \int \frac{\sqrt{1+y'^2}}{v} dx \quad (1)$$

Although we have  $v = v(y)$ , we only have  $dv/dy \neq 0$  when  $y = 0$ . The Euler equation tells us

$$\frac{d}{dx} \left[ \frac{y'}{v \sqrt{1+y'^2}} \right] = 0 \quad (2)$$

Now use  $v = c/n$  and  $y' = -\tan \theta$  to obtain

$$n \sin \theta = \text{const.} \quad (3)$$

This proves the assertion. Alternatively, Fermat's principle can be proven by the method introduced in the solution of Problem 6-8.

**6-12.** The path length is given by

$$s = \int ds = \int \sqrt{1 + y'^2 + z'^2} dx \quad (1)$$

and our equation of constraint is

$$g(x, y, z) = x^2 + y^2 + z^2 - \rho^2 = 0 \quad (2)$$

The Euler equations with undetermined multipliers (6.69) tell us that

$$\frac{d}{dx} \left[ \frac{y'}{\sqrt{1 + y'^2 + z'^2}} \right] = \lambda \frac{dg}{dy} = 2\lambda y \quad (3)$$

with a similar equation for  $z$ . Eliminating the factor  $\lambda$ , we obtain

$$\frac{1}{y} \frac{d}{dx} \left[ \frac{y'}{\sqrt{1 + y'^2 + z'^2}} \right] - \frac{1}{z} \frac{d}{dx} \left[ \frac{z'}{\sqrt{1 + y'^2 + z'^2}} \right] = 0 \quad (4)$$

This simplifies to

$$z \left[ y''(1 + y'^2 + z'^2) - y'(y'y'' + z'z'') \right] - y \left[ z''(1 + y'^2 + z'^2) - z'(y'y'' + z'z'') \right] = 0 \quad (5)$$

$$zy'' + (yy' + zz')z'y'' - yz'' - (yy' + zz')y'z'' = 0 \quad (6)$$

and using the derivative of (2),

$$(z - xz')y'' = (y - xy')z'' \quad (7)$$

This looks to be in the simplest form we can make it, but is it a plane? Take the equation of a plane passing through the origin:

$$Ax + By = z \quad (8)$$

and make it a differential equation by taking derivatives (giving  $A + By' = z'$  and  $By'' = z''$ ) and eliminating the constants. The substitution yields (7) exactly. This confirms that the path must be the intersection of the sphere with a plane passing through the origin, as required.