

Given

$$A = \begin{bmatrix} -3 & \sqrt{2} \\ \sqrt{2} & -2 \end{bmatrix} \quad \text{for} \quad \frac{d\vec{Y}}{dt} = A\vec{Y}$$

a) Eigenvalues:

$$\det(A - \lambda I) = \det \begin{pmatrix} -3-\lambda & \sqrt{2} \\ \sqrt{2} & -2-\lambda \end{pmatrix} =$$

$$= (-3-\lambda)(-2-\lambda) + -2 = \lambda^2 + 5\lambda + 4 = (\lambda+4)(\lambda+1) = 0$$

$$\Rightarrow \lambda_1 = -1$$

$$\lambda_2 = -4$$

b)

Case  $\lambda_1 = -1$ :

$$(A - \lambda I)\vec{v} = \vec{0}$$

$$\begin{bmatrix} -3+1 & \sqrt{2} \\ \sqrt{2} & -2+1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow -2v_1 + \sqrt{2}v_2 = 0$$

let  $v_1 = \sqrt{2} \Rightarrow \vec{v}^{(1)} = \begin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix}$   
 $v_2 = 2$

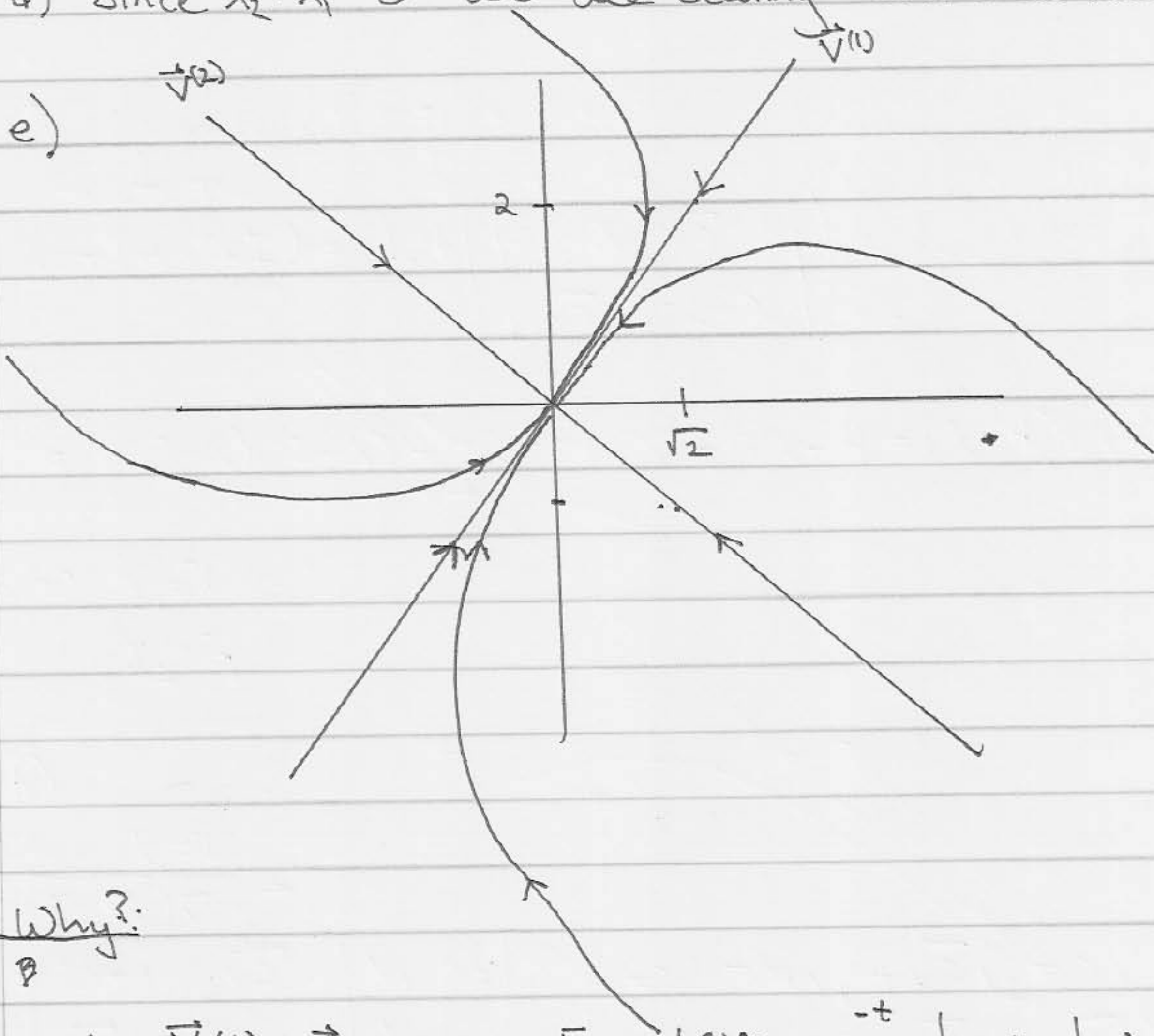
Case  $\lambda_2 = -4$ :

$$\begin{bmatrix} -3+4 & \sqrt{2} \\ \sqrt{2} & -2+4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow v_1 + \sqrt{2}v_2 = 0$$

let  $v_1 = \sqrt{2} \Rightarrow \vec{v}^{(2)} = \begin{bmatrix} \sqrt{2} \\ -1 \end{bmatrix}$   
 $v_2 = -1$

$$c) \vec{Y}(t) = k_1 \begin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix} e^{-t} + k_2 \begin{bmatrix} \sqrt{2} \\ -1 \end{bmatrix} e^{-4t}$$

d) Since  $\lambda_2 < \lambda_1 < 0$  we are dealing with a Real sink.



Why?

- $\lim_{t \rightarrow \infty} \vec{Y}(t) = \vec{0}$

- For  $t \rightarrow \infty$   $e^{-t}$  dominates

so soln are asymptotically like  $\begin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix}$

- For  $t \rightarrow -\infty$   $e^{-4t}$  dominates so soln is asymptotically like  $\begin{bmatrix} \sqrt{2} \\ -1 \end{bmatrix}$

f)  $\vec{Y}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = k_1 \begin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix} + k_2 \begin{bmatrix} \sqrt{2} \\ -1 \end{bmatrix} \Rightarrow 2k_1 = k_2$   
 $1 = \sqrt{2}k_1 + \sqrt{2}k_2 = \sqrt{2}k_1 + 2\sqrt{2}k_1 \Rightarrow k_1 = \frac{1}{3\sqrt{2}}$   
 $k_2 = \frac{2}{3\sqrt{2}}$

and  $\vec{Y}(t) = \frac{1}{3\sqrt{2}} \begin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix} e^{-t} + \frac{2}{3\sqrt{2}} \begin{bmatrix} \sqrt{2} \\ -1 \end{bmatrix} e^{-4t}$



Given,

$$A = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix} \quad \text{for} \quad \frac{d\vec{Y}}{dt} = A\vec{Y}$$

a) Eigenvalues:

$$\det(A - \lambda I) = \det \begin{pmatrix} 1-\lambda & 1 \\ 4 & 1-\lambda \end{pmatrix} = (1-\lambda)^2 - 4 =$$

$$= \lambda^2 - 2\lambda + 1 - 4 = \lambda^2 - 2\lambda - 3 = 0$$
$$(\lambda+1)(\lambda-3) = 0$$

$$\Rightarrow \lambda_1 = -1$$

$$\lambda_2 = 3$$

b) Eigenvectors

Case  $\lambda_1 = -1$ :

$$(A - \lambda_1 I)\vec{v} = \begin{bmatrix} 1 - (-1) & 1 \\ 4 & 1 - (-1) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{aligned} 2v_1 + v_2 &= 0 \Rightarrow 2v_1 = -v_2 \\ 4v_1 + 2v_2 &= 0 \end{aligned}$$

if we let  $v_1 = 1$  then  $v_2 = -2 \Rightarrow \vec{v}^{(1)} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$

\* We can do this in  $\mathbb{R}^2$  since any  $\uparrow$  Eigenvector is again an  
Eigenvector. constant multiple of an

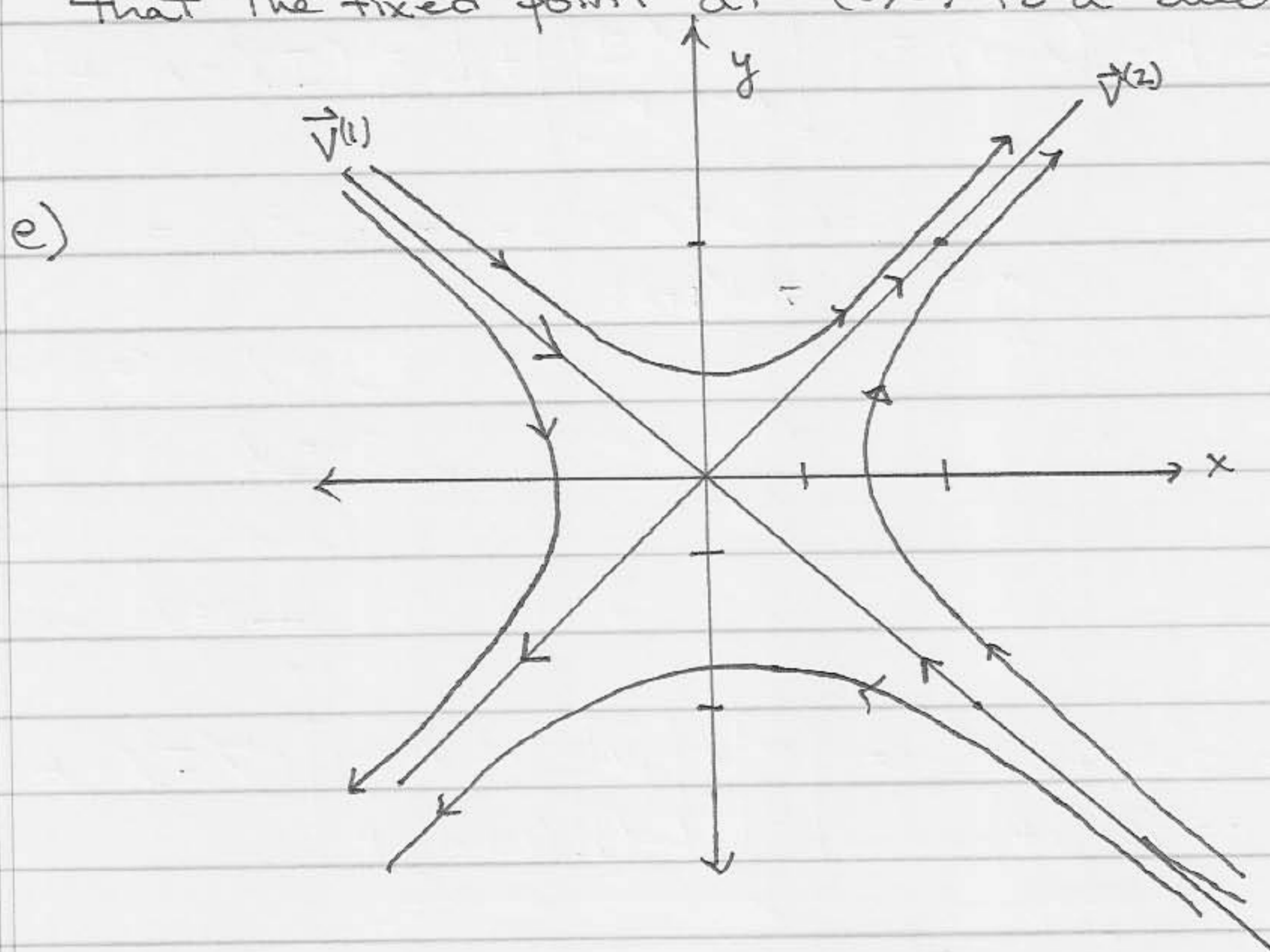
Case  $\lambda_2 = 3$ :

$$(A - \lambda_2 I)\vec{v} = \begin{bmatrix} -2 & 1 \\ 4 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \vec{v}^{(2)} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

c) General Soln.

$$\vec{Y}(t) = k_1 \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-t} + k_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{3t}, \quad k_1, k_2 \in \mathbb{R}$$

d) Since  $\lambda_1 = -1 < 0 < 3 = \lambda_2$  we conclude that the fixed point at  $(0,0)$  is a saddle.



Why:

• If the initial condition is such that  $k_1 = 0$  then  $e^{3t} \rightarrow$  growth along  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

• If the initial condition is such that  $k_2 = 0$  then  $e^{-t} \rightarrow$  decay along  $\begin{bmatrix} 1 \\ -2 \end{bmatrix}$

• If  $t \rightarrow -\infty$  then  $e^{3t} \approx 0$  and the soln is asymptotic to  $\begin{bmatrix} 1 \\ -2 \end{bmatrix}$ . If  $t \rightarrow \infty$  then  $e^{-t} \approx 0$  Soln is asy. to  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$