

1. Given

$$(1) \quad my'' + ky = 0, \quad y(0) = -1, \quad y'(0) = +1$$

a) Let $\frac{dy}{dt} = y' = v$ then (1) becomes,

$$\frac{dv}{dt} = v' = -\frac{ky}{m} \Rightarrow \frac{dy}{dt} = v \quad \Leftrightarrow \quad \frac{d}{dt} \begin{bmatrix} y \\ v \end{bmatrix} = \overbrace{\begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & 0 \end{bmatrix}}^A \begin{bmatrix} y \\ v \end{bmatrix}$$

where the initial cond.

gives

$$\vec{Y}(0) = \begin{bmatrix} y(0) \\ v(0) \end{bmatrix} = \begin{bmatrix} -1 \\ +1 \end{bmatrix}$$

b)

$$\det(A - \lambda I) = \lambda^2 + \frac{k}{m} = 0 \Rightarrow \lambda = \pm \sqrt{-\frac{k}{m}} =$$

$$= \pm \sqrt{\frac{k}{m}} i = \pm \omega_0 i$$

Case $\lambda_1 = \omega_0 i$

$$(A - \lambda_1 I) \vec{v} = \begin{bmatrix} -\omega_0 i & 1 \\ -\frac{k}{m} & -\omega_0 i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad \omega_0 v_1 = v_2 \Rightarrow \vec{v}^{(1)} = \begin{bmatrix} 1 \\ \omega_0 i \end{bmatrix}$$

$$\Rightarrow \vec{Y}(t) = k_1 \begin{bmatrix} 1 \\ \omega_0 i \end{bmatrix} e^{\omega_0 i t} + k_2 \begin{bmatrix} 1 \\ -\omega_0 i \end{bmatrix} e^{-\omega_0 i t}$$

(c) Equilibrium is a Center.

or

$$\vec{Y}_{\text{Real}}(t) = k_1 \begin{bmatrix} \cos(\omega_0 t) \\ -\omega_0 \sin(\omega_0 t) \end{bmatrix} + k_2 \begin{bmatrix} \sin(\omega_0 t) \\ \cos(\omega_0 t) \end{bmatrix}$$

$$\vec{Y}(0) = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \Rightarrow k_1 = -1, \quad k_2 = 1$$

