

Linear Independence - Matrix Spaces - Vector Spaces

1. Determine the values of h for which the vectors are linearly dependent.

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ -3 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -5 \\ 7 \\ 8 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ h \end{bmatrix}$$

2. Given,

$$\mathbf{A} = \begin{bmatrix} -8 & -2 & -9 \\ 6 & 4 & 8 \\ 4 & 0 & 4 \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}.$$

- (a) Is \mathbf{w} in the column space of \mathbf{A} ? That is, does $\mathbf{w} \in \text{Col } \mathbf{A}$?
 (b) Is \mathbf{w} in the null space of \mathbf{A} ? That is, does $\mathbf{w} \in \text{Nul } \mathbf{A}$?

3. Given,

$$\mathbf{A} = \begin{bmatrix} 2 & -3 & 6 & 2 & 5 \\ -2 & 3 & -3 & -3 & -4 \\ 4 & -6 & 9 & 5 & 9 \\ -2 & 3 & 3 & -4 & 1 \end{bmatrix}.$$

Determine:

- (a) The basis and dimension of $\text{Nul } \mathbf{A}$.
 (b) The basis and dimension of $\text{Col } \mathbf{A}$.
 (c) The basis and dimension of $\text{Row } \mathbf{A}$.
 (d) What is the Rank of \mathbf{A} ?

4. Let,

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 4 \\ 2 \\ 6 \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}.$$

- (a) How many vectors are in $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$?
 (b) How many vectors are in $\text{Span } \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$?
 (c) Is \mathbf{w} in $\text{Span } \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$?

5. Given,

$$my'' + ky = 0, \quad m, k \in \mathbb{R}. \quad (1)$$

- (a) Show that $y_1(t) = \cos(\omega t)$ and $y_2(t) = \sin(\omega t)$, where $\omega = \sqrt{\frac{k}{m}}$, are solutions to the ODE.
 (b) Show that any function in $\text{Span}\{y_1, y_2\}$ is a solution to the ODE.¹

¹Since we know from differential equations that the only solutions to (1) are $0, y_1, y_2$ we can conclude that the space of solutions to (1) forms a vector space whose basis is y_1 and y_2 .