

MATH 235 - SPRING 2008

HOMEWORK 2

1] (a) SHOW THAT $y(t) = e^{2t} + Ce^t$ $C \in \mathbb{R}$

IS A SOLUTION TO $\frac{dy}{dt} - y = e^{2t}$

$$y = e^{2t} + Ce^t$$

$$\frac{dy}{dt} = 2e^{2t} + Ce^t$$

SUBSTITUTING INTO THE O.D.E. WE GET

$$2e^{2t} + Ce^t - (e^{2t} + Ce^t) = e^{2t}$$

$$\Rightarrow e^{2t} = e^{2t}$$

(b) SHOW THAT $x^2 + y^2 = cx$ $C \in \mathbb{R}$

IS A SOLUTION TO $2xy \frac{dy}{dx} = y^2 - x^2$

$$\frac{d}{dx} [x^2 + y^2 = cx] \Rightarrow 2x + 2y \frac{dy}{dx} = c \Rightarrow \frac{dy}{dx} = \frac{c - 2x}{2y}$$

SUBSTITUTING INTO THE O.D.E.:

$$2xy \left(\frac{c - 2x}{2y} \right) = y^2 - x^2 \Rightarrow cx - 2x^2 = y^2 - x^2$$

$$\Rightarrow (x^2 + y^2) - 2x^2 = y^2 - x^2 \Rightarrow y^2 - x^2 = y^2 - x^2$$

(c) SHOW THAT $y(t) = C_1 \sinh(t) + C_2 \cosh(t)$
IS A SOLUTION TO $y'' - y = 0$

$$y = C_1 \sinh(t) + C_2 \cosh(t)$$

$$y' = C_1 \cosh(t) + C_2 \sinh(t)$$

$$y'' = C_1 \sinh(t) + C_2 \cosh(t)$$

SUBSTITUTING INTO THE O.D.E.:

$$C_1 \sinh(t) + C_2 \cosh(t) - (C_1 \sinh(t) + C_2 \cosh(t)) = 0$$

$$\Rightarrow 0 = 0$$

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(d) SHOW THAT $y(t) = C_1 \cos(t) + C_2 \sin(t)$ $C_1, C_2 \in \mathbb{R}$
IS A SOLUTION TO $y'' + y = 0$

$$y = C_1 \cos(t) + C_2 \sin(t)$$

$$y' = -C_1 \sin(t) + C_2 \cos(t)$$

$$y'' = -C_1 \cos(t) - C_2 \sin(t)$$

SUBSTITUTING INTO THE O.D.E. :

$$-C_1 \cos(t) - C_2 \sin(t) + C_1 \cos(t) + C_2 \sin(t) = 0$$

$$\Rightarrow 0 = 0$$

(e) SHOW THAT $x(t) = Ae^{-k_1 t}$ AND

$$y(t) = \frac{k_1 A}{k_1 - k_2} e^{-k_2 t} + \frac{k_1 A}{k_2 - k_1} e^{k_1 t}$$

ARE SOLUTIONS TO THE SYSTEM OF O.D.E.'S

$$\frac{dx}{dt} = -k_1 x \quad x(0) = A$$

$$\frac{dy}{dt} = k_1 x - k_2 y \quad y(0) = 0$$

$$x = Ae^{-k_1 t}$$

$$\frac{dx}{dt} = -k_1 A e^{-k_1 t} = -k_1 x$$

$$y = \frac{k_1 A}{k_1 - k_2} e^{-k_2 t} + \frac{k_1 A}{k_2 - k_1} e^{-k_1 t}$$

$$\frac{dy}{dt} = \frac{-k_2 k_1 A e^{-k_2 t}}{k_1 - k_2} + \frac{-k_1^2 A e^{-k_1 t}}{k_2 - k_1}$$

$$= \frac{-k_2 k_1 A e^{-k_2 t}}{k_1 - k_2} + \frac{-k_1^2 A e^{-k_1 t} + k_1 k_2 A e^{-k_1 t} - k_1 k_2 A e^{-k_1 t}}{k_2 - k_1}$$

HW #1 - Solutions MACS325

1. a. Assumptions:

- The rate of growth is negative if the population is too small.
- The rate of growth is negative if the population is too big.
- If $P=0$ then $\frac{dP}{dt} = 0$.

Variables/Parameters:

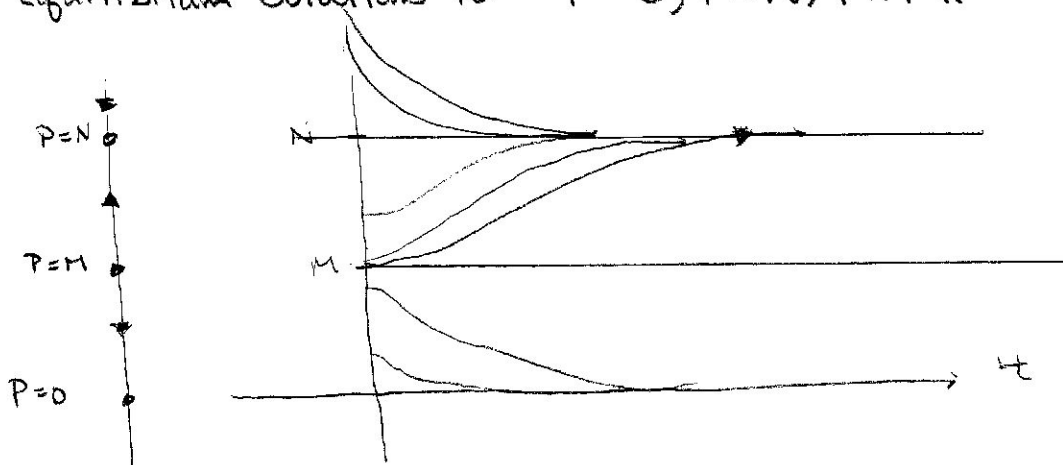
- t - time, (independent)
- P - Population (dependent)
- k - growth rate (parameter)
- N - Carrying Capacity (Parameter)
- M - Sparsity const (Parameter)

Model:

$$\frac{dP}{dt} = kP(1 - P/N)\left(\frac{P}{M} - 1\right), \text{ where } M < N.$$

Note: if $0 < P < M \Rightarrow (P/M - 1) < 0 \Rightarrow \frac{dP}{dt} < 0$
 $P > N \Rightarrow (1 - P/N) < 0 \Rightarrow \frac{dP}{dt} < 0$

b. Equilibrium Solutions for $P=0, P=N, P=M$.



$$c. \quad \frac{dp}{dt} = kP(1-P/N)(P/M-1) \Leftrightarrow \frac{dp}{kP(1-P/N)(P/M-1)} = dt$$

$$C(kP)(1-P/N)$$

\Rightarrow (Partial Fractions)

$$\frac{1}{kP(1-P/N)(P/M-1)} = \frac{A}{kP} + \frac{B}{(1-P/N)} + \frac{C}{(P/M-1)} = \frac{A(1-P/N)(P/M-1) + B(kP)(P/M-1) + C(kP)(1-P/N)}{kP(1-P/N)(P/M-1)}$$

$$\Rightarrow A(1-P/N)(P/M-1) + B(kP)(P/M-1) + C(kP)(1-P/N) = 1$$

for $P=0$ $A = -1$

$P=N$ $B(kN)(N/M-1) = 1 \Rightarrow B = \frac{1}{kN(N/M-1)}$

$P=M$ $C = \frac{1}{kM(1-M/N)}$

Thus

$$\int \frac{dp}{kP(1-P/N)(P/M-1)} = \int \left\{ \frac{-1}{kP} + \frac{[\frac{1}{kN(N/M-1)}]^{-1}}{1-P/N} + \frac{[\frac{1}{kM(1-M/N)}]^{-1}}{P/M-1} \right\} dp =$$

$$= -\ln|kP| - N \left[\frac{1}{kN(N/M-1)} \right]^{-1} \ln|1-P/N| + M \left[\frac{1}{kM(1-M/N)} \right]^{-1} \ln|P/M-1| =$$

$$= \ln \left| \frac{(P/M-1)^M [kM(1-M/N)]^{-1}}{kP(1-P/N)^N [kN(N/M-1)]^{-1}} \right| = \ln \left| \frac{(P/M-1)^M \frac{1}{k(1-M/N)}}{kP(1-P/N)^N \frac{1}{k(N/M-1)}} \right| = \int dt =$$

$$= t + C$$

Thus,

$$\frac{\left(\frac{P}{M} - 1\right)^{\frac{1}{R(1-M/N)}}}{RP \left(1 - \frac{P}{N}\right)^{\frac{1}{R(N/M-1)}}} = \pm e^{ct} = ke^t, \quad k \in \mathbb{R}.$$

2 a) In this case

$x(t)$ is the prey

$y(t)$ is the predator.

Why?

- Terms with both x, y are interaction terms and dictate the effect x, y have on each other.

Since (1) has a negative yx term the effect of the interaction on the growth of $x(t)$ is negative. Thus, $x(t)$ decays if $y(t)$ is large. NKA y eats x .

Similarly $y(t)$ is the prey since the interaction is favorable.

b. If $x(t) = 0$ for all t then $\frac{dy}{dt} = 0 \Rightarrow y(t) = C, C \in \mathbb{R}$.
There must be a secondary food source.

$$a. \frac{dy}{dt} = 1 + \frac{1}{y^2} \Leftrightarrow \frac{dy}{1 + 1/y^2} = \int \frac{y^2}{1+y^2} dy = \int dt \Leftrightarrow$$

$$\Leftrightarrow \int \frac{y^2}{1+y^2} dy = \int \left\{ 1 - \frac{1}{1+y^2} \right\} dy = y - \arctan(y) = t + c$$

$$\Rightarrow y - \arctan(y) = t + c \quad (\text{Implicit})$$

$$b. (y')^2 - xy' + y = (y')^2 - xy' + \frac{x^2}{4} - \frac{x^2}{4} + y =$$

$$= \left(y' - \frac{x}{2} \right)^2 + y - \frac{x^2}{4} = 0 \quad (1)$$

$$\text{Let } z = -y + \frac{x^2}{4} \Rightarrow \frac{dz}{dx} = -\frac{dy}{dx} + \frac{2x}{4} = -y' + \frac{x}{2} = z'$$

thus (1) becomes

$$\left(y' - \frac{x}{2} \right)^2 + y - \frac{x^2}{4} = (-z')^2 - z = 0 \Leftrightarrow$$

$$\Leftrightarrow \frac{dz}{dx} = -\sqrt{-z} \Leftrightarrow \int \frac{dz}{\sqrt{-z}} = \int -dx$$

\Rightarrow

$$2\sqrt{-z} = -x + c \Leftrightarrow \sqrt{-z} = -\frac{x}{2} + c, \quad -\frac{x}{2} + c > 0$$

$$\Rightarrow z = \left(-\frac{x}{2} + c \right)^2 = -y + \frac{x^2}{4} \Rightarrow y(x) = \frac{x^2}{4} - \left(-\frac{x}{2} + c \right)^2 =$$

$$= -cx + c^2, \quad -\frac{x}{2} + c > 0.$$

$$c \quad \frac{dy}{dt} = (y^2+1)t, \quad y(0)=1$$

$$\Rightarrow \int \frac{dy}{y^2+1} = \int t dt \Leftrightarrow \arctan(y) = \frac{1}{2}t^2 + c$$

$$\Rightarrow y(t) = \tan\left(\frac{1}{2}t^2 + c\right) \text{ [general soln]}$$

Application of the initial condition:

$$y(0) = 1 = \tan(0+c) \Rightarrow c = \frac{\pi}{4} \text{ (any } n\pi \text{ multiple should work as well)}$$

\Rightarrow

$$y(t) = \tan\left(\frac{1}{2}t^2 + n\frac{\pi}{4}\right) \text{ [is the unique soln to the IVP.]}$$

4. Assume that $y(t) = 2$, $\forall t \in \mathbb{R}$ is a solution to $\frac{dy}{dt} = f(t, y)$.

a) If $y(t) = 2$ then $\frac{dy}{dt} = 0 = f(t, 2)$, $\forall t \in \mathbb{R}$

b) From this information all we can sketch is the slope field for $y = 2$.

c) From this we know that solutions starting above $y = 2$ must stay above $y = 2$ and solutions below $y = 2$ must stay below $y = 2$ for all time.

5. a) See attached

b) See attached.

c) The roots of $p(y)$ are equilibrium solutions to the differential equation $\frac{dy}{dt} = p(y)$.

d) See attached.

1.4 Example 1 - B

k	t _k	y _k	f(t _k , y _k)	delta t
0	0	0.5	0.875	0.125
1	0.125	0.609375	0.554966	
2	0.25	0.67874575	0.329813	
3	0.375	0.7199724	0.18685	
4	0.5	0.74332866	0.102626	
5	0.625	0.75615688	0.055336	
6	0.75	0.76307388	0.029528	
7	0.875	0.76676491	0.015667	
8	1	0.76872332	0.008287	
9	1.125	0.76975925	0.004377	
10	1.25	0.77030632	0.002309	
11	1.375	0.77059498	0.001218	
12	1.5	0.77074722	0.000642	
13	1.625	0.7708275	0.000339	
14	1.75	0.77086982	0.000178	
15	1.875	0.77089213	9.41E-05	
16	2	0.77090389	4.96E-05	
17	2.125	0.77091009	2.61E-05	
18	2.25	0.77091335	1.38E-05	
19	2.375	0.77091508	7.26E-06	
20	2.5	0.77091598	3.83E-06	
21	2.625	0.77091646	2.02E-06	
22	2.75	0.77091672	1.06E-06	

