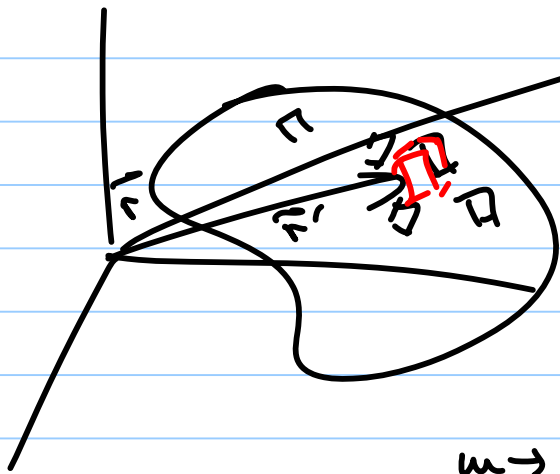


Permanent $\left\{ \begin{array}{l} P \\ S \end{array} \right\}$ \rightarrow rept, dipole $\left\{ \begin{array}{l} B \\ \end{array} \right\}$

$$\mathcal{E}_{\text{inf}} = - \frac{d\Phi}{dt}$$



details



first \vec{B} first \vec{A}_{dipole}

$$\vec{A} = \frac{\mu_0}{4\pi} \frac{\vec{n} \times \hat{n}}{r^2}$$

\leftarrow dipole moment for an element

$m \rightarrow \vec{M} \text{ dt}$
 \uparrow
 dipole moment

$\rho \text{ dt} = dm$
 $\frac{\text{mass}}{\text{vol}}$

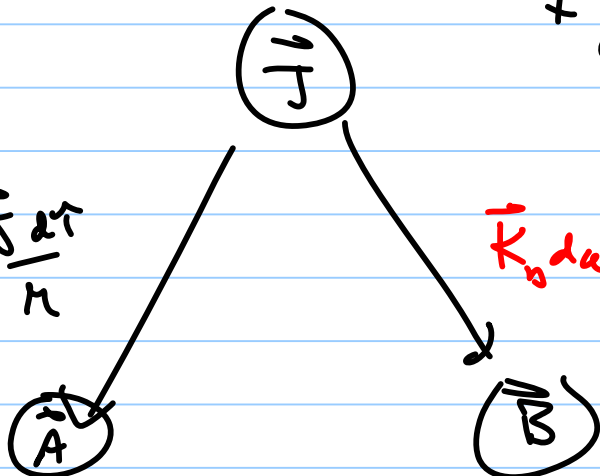
$$\int d\vec{A} = \vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{M} + \hat{n}}{r^2} d\vec{r} = \frac{\mu_0}{4\pi} \int \frac{\nabla \times \vec{M}}{r} d\vec{r}$$

$$\vec{B} = \vec{\nabla} \times \vec{A}$$

$$+ \frac{\mu_0}{4\pi} \int \frac{\vec{M} \times \hat{n}}{r} d\vec{r}$$

$$\vec{K}_b \text{ da} = \vec{M} \times \hat{n} \text{ da}$$

$$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{J} \text{ dt}}{r}$$



Given \vec{M} find $\vec{J}_b = \nabla \times \vec{M} \neq \vec{K}_b$

Review

$$dV_{\text{dipole}} = V = \int \frac{\vec{\nabla} \cdot \vec{P}}{r} d\tau + \int \frac{\vec{P} \cdot \hat{n} da}{r}$$

$$V = \int \frac{\vec{P} \cdot \hat{n}}{r} d\tau$$

$$\vec{M} = M_0 \hat{z}$$

$$\vec{J}_b = \nabla \times \vec{M} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & M_0 \end{vmatrix}$$

$$\vec{K}_b = \vec{M} \times \hat{n} da = M_0 \hat{z} \times \hat{s} da$$

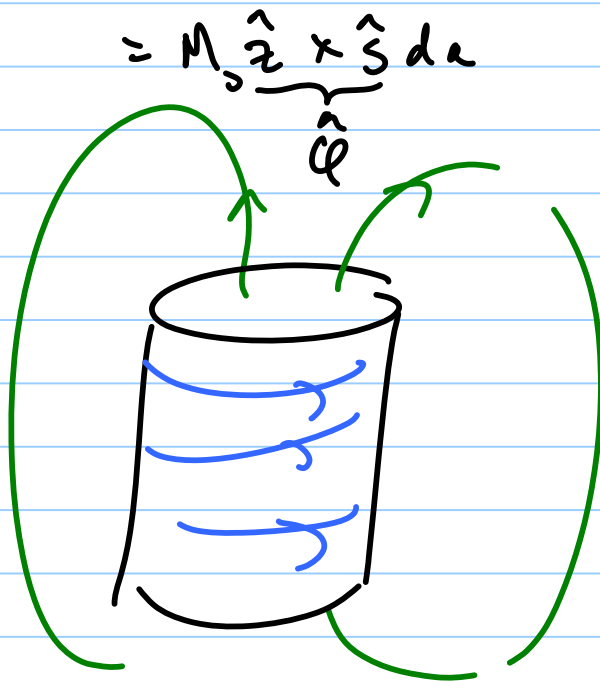
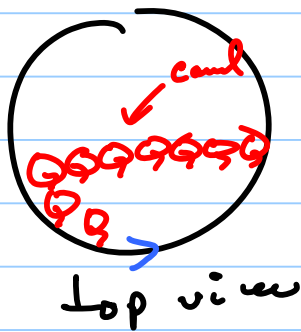


$$\vec{M} = M_0 \hat{z}$$

$$\vec{J}_b = \nabla \times \vec{M} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & M_0 \end{vmatrix}$$

$$\vec{K}_b = \vec{M} \times \hat{n} da$$

$$= M_0 \hat{z} \times \hat{s} da$$



Problem is to find \vec{M}

- approx that material is linear

Start with amp's law

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

$$\frac{1}{\mu_0} \vec{\nabla} \times \vec{B} = \vec{J} = \vec{J}_f + \vec{J}_b + \cancel{\vec{J}} \text{ displacement}$$

$$\vec{\nabla} \times \vec{M}$$

$$\vec{\nabla} \times \left(\frac{\vec{B}}{\mu_0} - \vec{M} \right) = \vec{J}_f$$

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho_f}{\epsilon_0} = \frac{\rho_f}{\epsilon_0} + \frac{\rho_b}{\epsilon_0} = \frac{\rho_f}{\epsilon_0} - \vec{\nabla} \cdot \vec{P}$$

$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

apply Amp's Law

$$\vec{\nabla} \times \vec{H} = \vec{J}_f$$

Stokes th.

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{enclosed free}}$$

need $\vec{\nabla} \cdot \vec{H}$ to define H (boundary cond.)

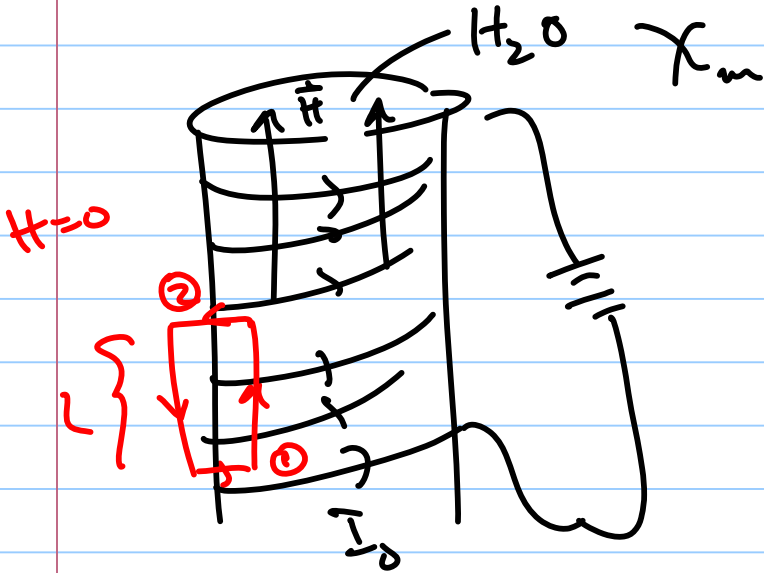
Assume linear material

$$\vec{M} = \chi_m \vec{H}$$

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M} = \frac{\vec{B}}{\mu_0} - \chi_m \vec{H}$$

$$\underbrace{\mu_0(1 + \chi_m)}_{\mu} \vec{H} = \vec{B}$$

change sign paramagnetic or diamagnetic



What is B in H_2O ?

Principle: Ampere Law $\oint \vec{H} \cdot d\vec{l} = I_{enc}^{free}$

$$Hl = I_0 n l$$

turns / length

$$H = n I_0$$

$$\vec{B} = \mu_0(1 + \chi_m) \vec{H} = \mu_0(1 + \chi_m) n I_0$$

↑
sign