

H₂O has electric dipole

$$\text{find } V(\vec{r}) = \int dV$$

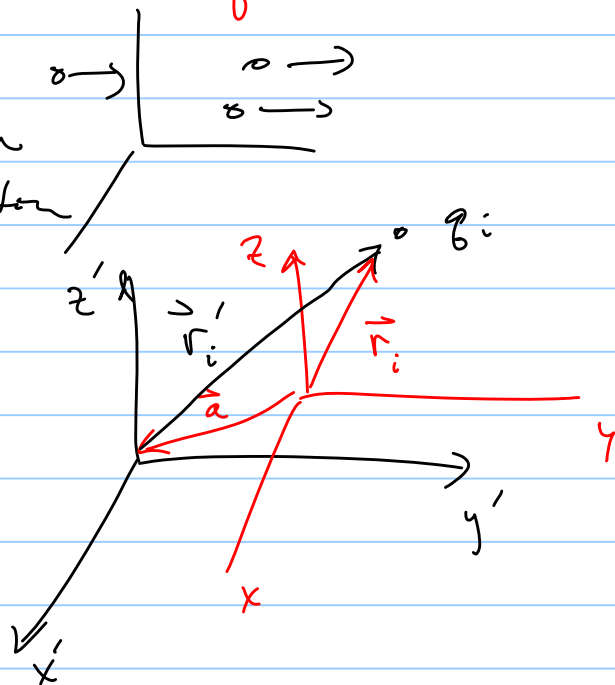
$$V_{\text{one dipole}} = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \hat{r}}{r^2}$$

\vec{p} must not depend on location of coords

mom inertia

$$I = \sum m_i r_i^2 \quad \text{depends on coord location}$$

$$\vec{p} = \sum q_i \vec{r}_i$$



$$\vec{r}'_i = \vec{a} + \vec{r}_i$$

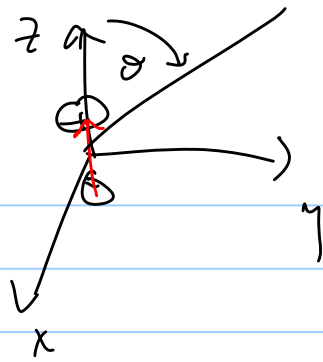
Is $\vec{p}' = \vec{p}$?

$$\vec{p}' = \sum q_i \vec{r}'_i = \sum q_i (\vec{r}_i - \vec{a}) = -\sum q_i \vec{a} + \underbrace{\sum q_i \vec{r}_i}_{\vec{p}}$$

$$= -\vec{a} \underbrace{\sum q_i}_0 + \vec{p}$$

NO NET CHARGE $\vec{p}' = \vec{p}$

$$V_{\text{one dipol}} = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \hat{r}}{r^2}$$



$$\vec{E} = -\nabla V$$

spherical

$$E_r = -\frac{\partial V}{\partial r}$$

$$V = \frac{1}{4\pi\epsilon_0} \frac{p \cos\theta}{r^2}$$

$$E_r = + \frac{2}{4\pi\epsilon_0} \frac{p \cos\theta}{r^3}$$

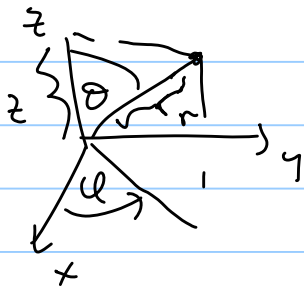
$$E_\theta = -\frac{1}{r} \frac{\partial V}{\partial \theta} = -\frac{1}{4\pi\epsilon_0 r} \frac{-p \sin\theta}{r^2}$$

$$= \frac{p \sin\theta}{4\pi\epsilon_0 r^3}$$

Cartesian:

$$V = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \hat{r}}{r^2}$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

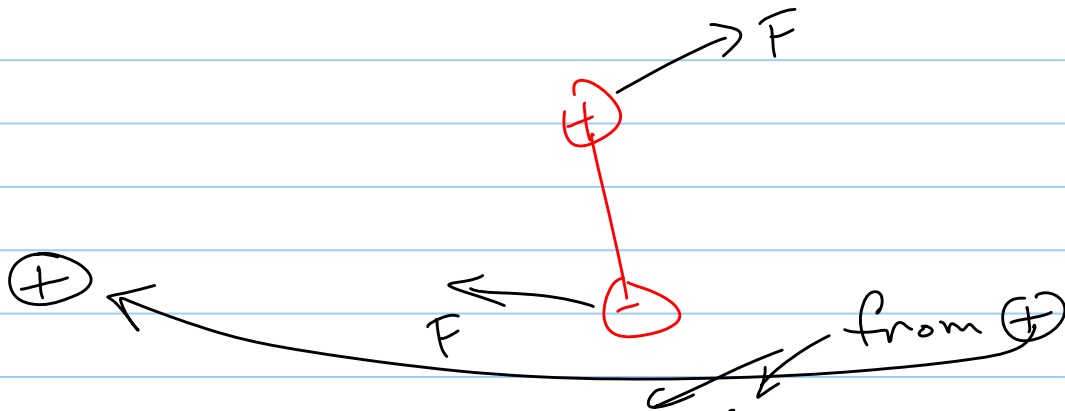
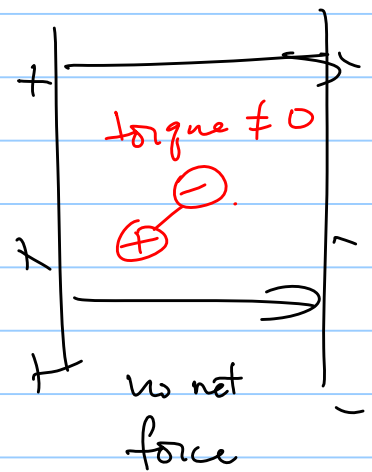
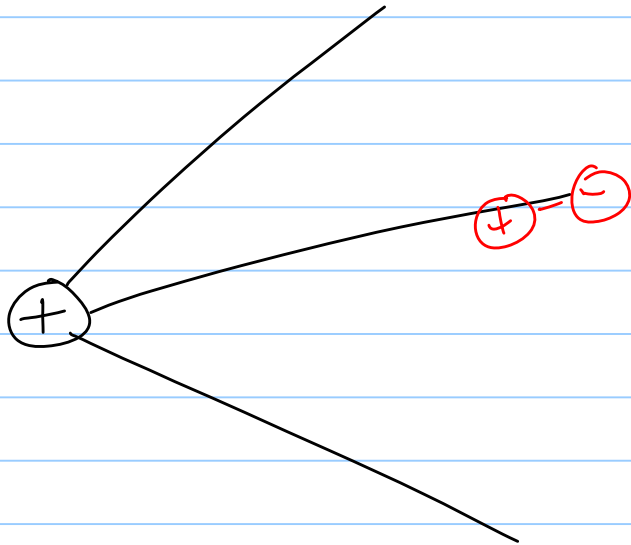
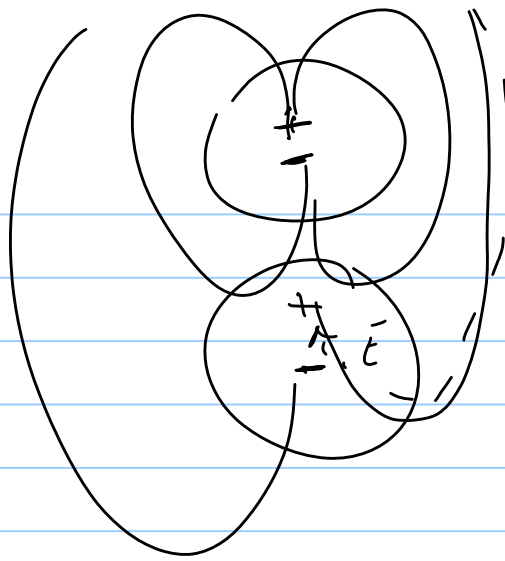


$$\cos\theta = \frac{z}{r} = \frac{z}{\sqrt{x^2 + y^2 + z^2}}$$

$$V = \frac{1}{4\pi\epsilon_0} \frac{p z}{(\sqrt{x^2 + y^2 + z^2})^3}$$

$$E_x = -\frac{\partial V}{\partial x}$$

Forces on a dipole



$$\vec{F}_{\text{net}} = \vec{F}_+ + \vec{F}_- = q(\vec{E}_+ - \vec{E}_-) = q \Delta \vec{E}$$

$$d\vec{E} = dE_x \hat{x} + dE_y \hat{y} + dE_z \hat{z}$$

$$d\bar{E}_x = \frac{\partial \bar{E}_x}{\partial x} dx + \frac{\partial \bar{E}_x}{\partial y} dy + \frac{\partial \bar{E}_x}{\partial z} dz$$

$$d\bar{E}_x = \left(\frac{\partial \bar{E}_x}{\partial x} \hat{x} + \frac{\partial \bar{E}_x}{\partial y} \hat{y} + \frac{\partial \bar{E}_x}{\partial z} \hat{z} \right) \cdot \left(dx \hat{x} + dy \hat{y} + dz \hat{z} \right)$$

$$\vec{\nabla} E_x$$

$$d\vec{l} = \vec{s} \text{ sep. of } dx, dy, dz$$

$$d\vec{E} = dE_x \hat{x} + dE_y \hat{y} + dE_z \hat{z}$$

$$\vec{F} = q d\vec{E} = q \left(d\vec{l} \cdot \vec{\nabla} \right) \vec{E} = \left(\vec{p} \cdot \vec{\nabla} \right) \vec{E}$$