

Least Squares - Orthogonal Diagonalization - Spectral Decomposition - Singular Value Decomposition

1. Given,

$$A = \begin{bmatrix} 2 & 4 \\ -5 & -1 \\ 1 & 2 \end{bmatrix}.$$

Determine an orthonormal basis for the column space of A .

2. Given the linear system of equations,

$$x_1 + x_3 = 2$$

$$x_1 + x_2 = 4$$

- Determine the least-squares solution to the linear system.
- Determine the least-squares error associated with the linear system.
- Graph the linear system, the least-squares solution, and the least-squares error in \mathbb{R}^3 .

3. Given,

$$A = \begin{bmatrix} 2 & 3 \\ 2 & 4 \\ 1 & 1 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix}.$$

- Show that the columns of A are linearly independent.
- Determine the QR factorization of A .
- Using this factorization calculate the unique least-squares solution $\hat{\mathbf{x}} = \mathbf{R}^{-1}\mathbf{Q}^T\mathbf{b}$.¹

4. Recall the Pauli Spin Matrix from a previous homework,

$$\sigma_x = \sigma_y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}.$$

- Show that σ_y is self-adjoint.²
- Find the orthogonal diagonalization of σ_y .³
- Show that $\sigma_y = \lambda_1\mathbf{x}_1\mathbf{x}_1^H + \lambda_2\mathbf{x}_2\mathbf{x}_2^H$, where \mathbf{x}_1 and \mathbf{x}_2 are the normalized eigenvectors from part (b).⁴

5. Given,

$$A = \begin{bmatrix} 7 & 1 \\ 0 & 0 \\ 5 & 5 \end{bmatrix}.$$

Find a singular value decomposition of A .

¹See theorem 6.5.15 on page 414.

²If a matrix is equal to its transpose then we say that the matrix is symmetric. If the matrix has complex numbers then we have a more general definition. For $A \in \mathbb{C}^{n \times n}$ we say that A is self-adjoint if $A^H = \bar{A}^T = A$. That is, a matrix is self-adjoint if it is equal to its own complex-conjugate transpose. Self-adjoint matrices are the analogue of symmetric matrices for the complex number field. Also, notice that this definition recovers the definition of symmetric if the matrix has only real entries.

³You should find eigenvectors with complex entries. If you use the standard definition of inner-product then you will get zero length, which is sensible since part of the direction of these vectors is into the complex number system. However, this will lead you to a division by zero when trying to normalize the eigenvector. In the case where vectors have complex entries the inner-product is generalised to $\mathbf{x} \cdot \mathbf{y} = \mathbf{x}^H\mathbf{y} = \bar{\mathbf{x}}^T\mathbf{y}$. Notice, again that the standard definition of inner-product is recovered when the vectors are real.

⁴This is called the spectral decomposition of a self-adjoint matrix. It is interesting to note that $\mathbf{x}_i^H\mathbf{x}_i = 1$, which implies that the 'matrix' has the same structure as the unitary matrices of chapter 6. Since, $\mathbf{x}_i\mathbf{x}_i^H$ is not the identity matrix we have that $\mathbf{x}_i\mathbf{x}_i^H$ has the same structure as unitary matrices from problem 3 in homework 8. Consequently, we conclude that the self-adjoint matrix has been decomposed into projection matrices, which project an arbitrary vector into eigen-subspaces of the original matrix.

5. A basis for the column space of A is $B_{\text{Col}A} = \{\vec{a}_1, \vec{a}_2\}$. Since $\vec{a}_1^T \vec{a}_2 \neq 0$, $B_{\text{Col}A}$ is not an orthogonal basis.

To form an orthogonal basis for the plane spanned by \vec{a}_1, \vec{a}_2 in \mathbb{R}^3 we use Gram-Schmidt.

Thus

$$\vec{v}_1 = \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix} = \vec{a}_1$$

$$\vec{v}_2 = \vec{a}_2 - \frac{\vec{a}_2^T \vec{v}_1}{\vec{v}_1^T \vec{v}_1} \vec{v}_1 = \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} - \frac{[4 \ -1 \ 2] \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}}{[2 \ -5 \ 1] \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix} =$$

$$= \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} - \frac{15}{30} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 1.5 \\ 1.5 \end{bmatrix}$$

Note $\vec{v}_1^T \vec{v}_2 = 6 - 7.5 + 1.5 = 0$

Thus $B_1 = \{\vec{v}_1, \vec{v}_2\}$ is an orthogonal basis for $\text{Col}A$. To form the orthonormal basis $\{\vec{u}_1, \vec{u}_2\}$ we normalize \vec{v}_1, \vec{v}_2 .

$$\vec{u}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{\sqrt{30}} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}, \quad \vec{u}_2 = \frac{\sqrt{2}}{\sqrt{27}} \begin{bmatrix} 3 \\ 1.5 \\ 1.5 \end{bmatrix}$$

$$2. (1) x_1 + x_2 = 2 \Rightarrow A\vec{x} = \vec{b}, A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, \vec{b} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}, \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$(2) x_1 + x_2 = 1$$

(a)

Clearly these lines never intersect. To solve the least squares problem for $A\vec{x} = \vec{b}$ we solve,

$$A^T A \vec{x} = A^T \vec{b}$$

where

$$A^T A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}$$

and

$$A^T \vec{b} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \end{bmatrix} = \begin{bmatrix} 6 \\ 6 \end{bmatrix}$$

which gives the augmented matrix,

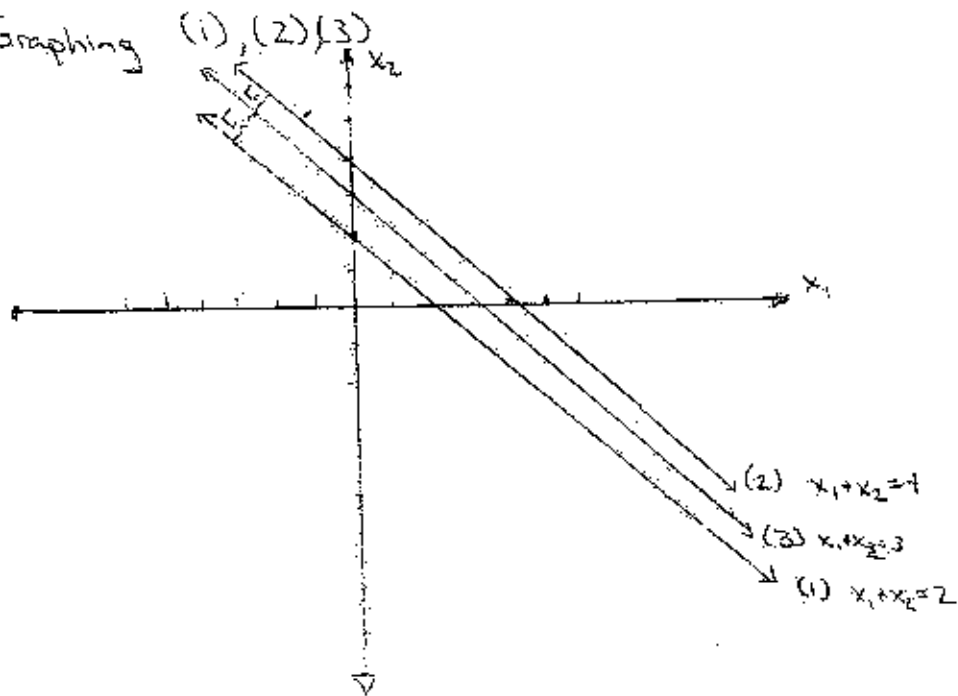
$$\left[\begin{array}{cc|c} 2 & 2 & 6 \\ 2 & 2 & 6 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 1 & 3 \\ 0 & 0 & 0 \end{array} \right] \Rightarrow x_1 + x_2 = 3 \text{ defines an } \infty\text{-amount of solutions.}$$

$$\text{In vector form this is: } \vec{x} = \begin{bmatrix} 3 - x_2 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} \quad (3)$$

(b) The least squares error is given by

$$\begin{aligned} \|\vec{b} - A\vec{x}\| &= \left\| \begin{bmatrix} 2 \\ 4 \end{bmatrix} - \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3 - x_2 \\ x_2 \end{bmatrix} \right\| = \left\| \begin{bmatrix} 2 \\ 4 \end{bmatrix} - \begin{bmatrix} 3 - x_2 + x_2 \\ 3 - x_2 + x_2 \end{bmatrix} \right\| = \\ &= \left\| \begin{bmatrix} 2 - 3 \\ 4 - 3 \end{bmatrix} \right\| = \left\| \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\| = \sqrt{2} \end{aligned}$$

c. Graphing



where $L = \sqrt{2}$. That is the distance between (1),(2) and (2),(3) is $\sqrt{2}$.

3. Let $A = \begin{bmatrix} 2 & 3 \\ 2 & 4 \\ 1 & 1 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix}$

a. To show that the columns are linearly independent you can Row Reduce $[A \mid 0]$ to show that only the trivial solution exists.

$$\left[\begin{array}{cc|c} 2 & 3 & 0 \\ 2 & 4 & 0 \\ 1 & 1 & 0 \end{array} \right] \sim \left[\begin{array}{cc|c} 2 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{array} \right] \Rightarrow x_2 = 0 \Rightarrow x_1 = 0$$

It is also pretty clear by looking at them that there is no constant c s.t. $\vec{a}_1 = c\vec{a}_2$.

b. Using \vec{a}_1, \vec{a}_2 apply G.S.

$$\vec{v}_1 = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$

$$\vec{v}_2 = \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix} - \frac{6+8+1}{4+4+1} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix} - \frac{5}{3} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -1/3 \\ 2/3 \\ -2/3 \end{bmatrix}$$

Normalizing gives

$$\vec{q}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{3} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}, \quad \vec{q}_2 = \frac{1}{\|\vec{v}_2\|} \vec{v}_2 = \begin{bmatrix} -1/3 \\ 2/3 \\ -2/3 \end{bmatrix}$$

Which implies $Q = \begin{bmatrix} 2/3 & -1/3 \\ 2/3 & 2/3 \\ 1/3 & -2/3 \end{bmatrix}$ and

$$R = Q^T A = \begin{bmatrix} 2/3 & 2/3 & 1/3 \\ -1/3 & 2/3 & -2/3 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 2 & 4 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 5 \\ 0 & 1 \end{bmatrix} \Rightarrow R^{-1} = \frac{1}{\det(A)} \begin{bmatrix} 1 & -5 \\ 0 & 3 \end{bmatrix} \\ = \frac{1}{3} \begin{bmatrix} 1 & -5 \\ 0 & 3 \end{bmatrix}$$

c. Since the columns of A are linearly independent, a unique solution to $A^T A \bar{x} = A^T \bar{b}$ exists. Theorem 6.5.15 gives this unique solution in terms of the QR factorization of A as

$$\bar{x} = \frac{1}{3} \begin{bmatrix} 1 & -5 \\ 0 & 3 \end{bmatrix}_{2 \times 2} \begin{bmatrix} 2/3 & 2/3 & 1/3 \\ -1/3 & 2/3 & -2/3 \end{bmatrix}_{2 \times 3} \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix}_{3 \times 1} = \begin{bmatrix} 4 \\ -1 \end{bmatrix}_{2 \times 1}$$

4. Let $\hat{S}_Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$

a. $\hat{S}_Y^H = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = \hat{S}_Y \Rightarrow \hat{S}_Y$ is self adjoint.

b. $\det(\hat{S}_Y - \lambda I) = \lambda^2 - 1 = 0 \Rightarrow \lambda = \pm 1$

$\lambda_1 = 1$

$[\hat{S}_Y - I | 0] = \left[\begin{array}{cc|c} 1 & -i & 0 \\ i & -1 & 0 \end{array} \right] \Rightarrow \begin{array}{l} -x_1 - ix_2 = 0 \\ \Rightarrow x_1 = -ix_2 \\ x_2 \text{ free} \end{array} \quad \bar{x} = \begin{bmatrix} -ix_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} -i \\ 1 \end{bmatrix} \Rightarrow$

$\Rightarrow \bar{x}_1 = \begin{bmatrix} -i \\ 1 \end{bmatrix} \quad \vec{v}_1 = \frac{1}{\|\bar{x}_1\|} \bar{x}_1 = \frac{1}{\sqrt{x_1^T x_1}} \begin{bmatrix} -i \\ 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} -i \\ 1 \end{bmatrix}$ (normalized Eigenvector)

$\lambda_2 = -1$

$[\hat{S}_Y + I | 0] = \left[\begin{array}{cc|c} 1 & -i & 0 \\ i & 1 & 0 \end{array} \right] \Rightarrow \begin{array}{l} x_1 = ix_2 \\ x_2 \text{ free} \end{array} \quad \bar{x}_2 = \begin{bmatrix} i \\ 1 \end{bmatrix}, \vec{v}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} i \\ 1 \end{bmatrix}$

Thus,

$A = \begin{bmatrix} -1/\sqrt{2} & i/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -i/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$

P D P^H

$PP^H = \begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -i/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$
 $= \begin{bmatrix} 1/2 + 1/2 & -1/2 + 1/2 \\ 1/2 - 1/2 & 1/2 + 1/2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$$c. A = \lambda_1 \vec{v}_1 \vec{v}_1^H + \lambda_2 \vec{v}_2 \vec{v}_2^H =$$

$$= 1 \cdot \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} +1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} - 1 \cdot \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} =$$

$$= \begin{bmatrix} +1/2 & -1/2 \\ +1/2 & 1/2 \end{bmatrix} - \begin{bmatrix} +1/2 & 1/2 \\ -1/2 & 1/2 \end{bmatrix} = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

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IF $A = \begin{bmatrix} 7 & 1 \\ 0 & 0 \\ 5 & 5 \end{bmatrix}$ then $A^T A = \begin{bmatrix} 7 & 0 & 5 \\ 1 & 0 & 5 \\ 5 & 5 \end{bmatrix} \begin{bmatrix} 7 & 1 \\ 0 & 0 \\ 5 & 5 \end{bmatrix} = \begin{bmatrix} 74 & 32 \\ 32 & 26 \end{bmatrix}$

$$\det(A - \lambda I) = \det \begin{bmatrix} 74 - \lambda & 32 \\ 32 & 26 - \lambda \end{bmatrix} = (26 - \lambda)(74 - \lambda) - 32^2 =$$

$$= \lambda^2 - 100\lambda + 900 = (\lambda - 10)(\lambda - 90) = 0$$

$\Rightarrow \lambda_1 = 90$ (*) Note I have placed them in descending order for later.

$\lambda_2 = 10$

$\lambda_1 = 90:$

$$[A - \lambda_1 I | 0] \begin{bmatrix} 74 - 90 & 32 & | & 0 \\ 32 & 26 - 90 & | & 0 \end{bmatrix} \sim \begin{bmatrix} -16 & 32 & | & 0 \\ 32 & -64 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \Rightarrow \begin{array}{l} x_1 = 2x_2 \\ x_2 \text{ is free} \end{array}$$

$$\Rightarrow \vec{x} = \begin{bmatrix} 2 \\ 1 \end{bmatrix} x_2 \Rightarrow \text{normalizing } \vec{v}_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$\lambda_2 = 10$

$$\begin{bmatrix} 64 & 32 & | & 0 \\ 32 & 16 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 2 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \Rightarrow -2x_1 = x_2 \Rightarrow \vec{x} = \begin{bmatrix} x_1 \\ -2x_1 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

x_1 free

$$\Rightarrow \vec{v}_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

Thus $\sigma_1 = \sqrt{90}$, $\sigma_2 = \sqrt{10}$, $\vec{v}_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$, $\vec{v}_2 = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$

implies that

$$A_{3 \times 2} = U_{3 \times 3} \Sigma_{3 \times 2} V_{2 \times 2}^T$$

where

$$\Sigma = \begin{bmatrix} \sqrt{90} & 0 \\ 0 & \sqrt{10} \\ 0 & 0 \end{bmatrix} \quad V = \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ 1/\sqrt{5} & -2/\sqrt{5} \end{bmatrix}$$

To find $\vec{u}_{3 \times 3}$,

$$\vec{u}_1 = \frac{1}{\|A\vec{v}_1\|} A\vec{v}_1 = \frac{1}{\sigma_1} \begin{bmatrix} 7 \cdot 2/\sqrt{5} + 1/\sqrt{5} \\ 0 \\ 10/\sqrt{5} + 5/\sqrt{5} \end{bmatrix} = \frac{1}{\sqrt{90}} \begin{bmatrix} 15/\sqrt{5} \\ 0 \\ 15/\sqrt{5} \end{bmatrix}$$

$$\vec{u}_2 = \frac{1}{\|A\vec{v}_2\|} A\vec{v}_2 = \frac{1}{\sigma_2} \begin{bmatrix} 7/\sqrt{5} - 2/\sqrt{5} \\ 0 \\ 5/\sqrt{5} - 10/\sqrt{5} \end{bmatrix} = \frac{1}{\sqrt{10}} \begin{bmatrix} 5/\sqrt{5} \\ 0 \\ -5/\sqrt{5} \end{bmatrix}$$

To find \vec{u}_3 determine the normalized $x \in \mathbb{R}^3$ s.t.

$$\vec{u}_1^T x = 0, \quad \vec{u}_2^T x = 0$$

$$\vec{u}_1^T x = \left(\frac{15}{\sqrt{5}} x_1 + \frac{15}{\sqrt{5}} x_2 \right) \frac{1}{\sqrt{90}} = 0 \Rightarrow \begin{bmatrix} 15 & 0 & 15 & | & 0 \\ 5 & 0 & -5 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 30 & 0 & 0 & | & 0 \\ 5 & 0 & -5 & | & 0 \end{bmatrix}$$

$$\vec{u}_2^T x = \left(\frac{5}{\sqrt{5}} x_1 + \frac{-5}{\sqrt{5}} x_2 \right) \frac{1}{\sqrt{10}} = 0 \Rightarrow \begin{matrix} x_1 = 0 & x_2 = \text{free} \\ x_3 = 0 \end{matrix}$$

and,

$$\vec{u}_3 = \begin{bmatrix} 0 \\ x_2 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \text{ choose } \vec{x}_2 \text{ so that } \|\vec{u}_3\| = 1$$

$$\text{Then } U = \begin{bmatrix} 15/\sqrt{50} & 5/\sqrt{50} & 0 \\ 0 & 0 & 1 \\ 15/\sqrt{50} & -5/\sqrt{50} & 0 \end{bmatrix}$$

and

$$A = \begin{bmatrix} 15/\sqrt{50} & 5/\sqrt{50} & 0 \\ 0 & 0 & 1 \\ 15/\sqrt{50} & -5/\sqrt{50} & 0 \end{bmatrix} \begin{bmatrix} \sqrt{10} & 0 \\ 0 & \sqrt{10} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ 1/\sqrt{5} & -2/\sqrt{5} \end{bmatrix}$$