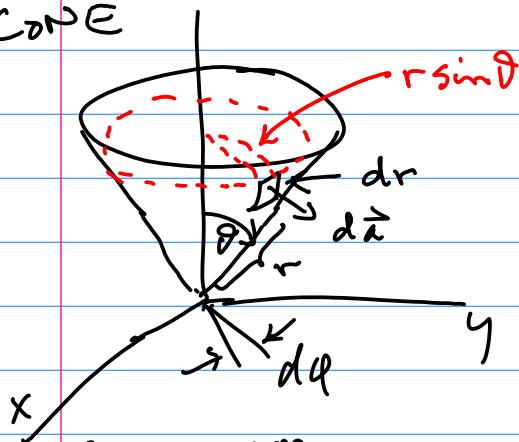


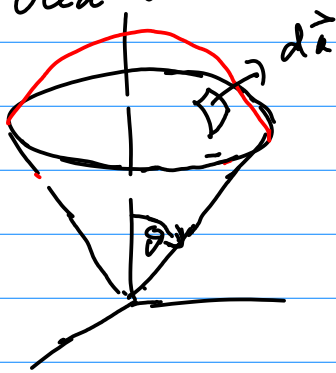
InkSurvey question for Monday

CONE



$$d\vec{a} = r \sin \theta d\phi dr \hat{\theta}$$

ice cream



$$d\vec{a} = r \sin \theta d\theta r d\theta \hat{r}$$

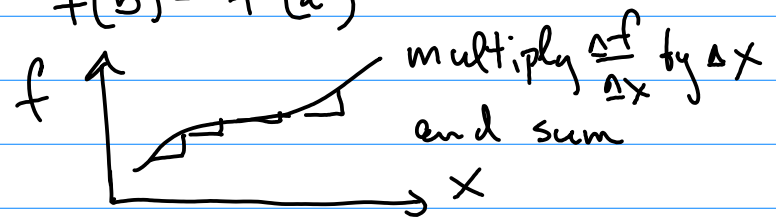
Using the spherical unit vectors is useful when calculating the flux given E in spherical coordinates. Then you have $E \cdot da$ where the unit vectors go away due to the dot product.

InkSurvey question for Monday

Fundamental theorem of calculus

$$\int_a^b \frac{df}{dx} dx = \int_a^b df = f(b) - f(a)$$

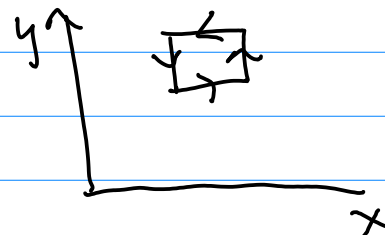
$\lim_{\Delta x \rightarrow 0} \frac{\Delta f}{\Delta x}$



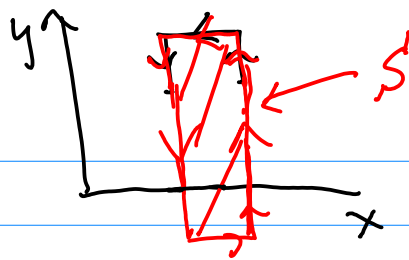
Defn of curl: $(\vec{\nabla} \times \vec{F})_z = \lim_{\Delta S_z \rightarrow 0} \left[\frac{1}{\Delta S_z} \oint_{C_z} \vec{F} \cdot d\vec{r} \right]$

multiply both sides by ΔS_z

$$\vec{\nabla} \times \vec{F} \cdot \Delta \vec{S} = \oint_{\text{around } \Delta S} \vec{F} \cdot d\vec{r}$$



$$\sum_S \vec{\nabla} \times \vec{F} \cdot \Delta \vec{S} = \oint_{\text{around } S} \vec{F} \cdot d\vec{r}$$



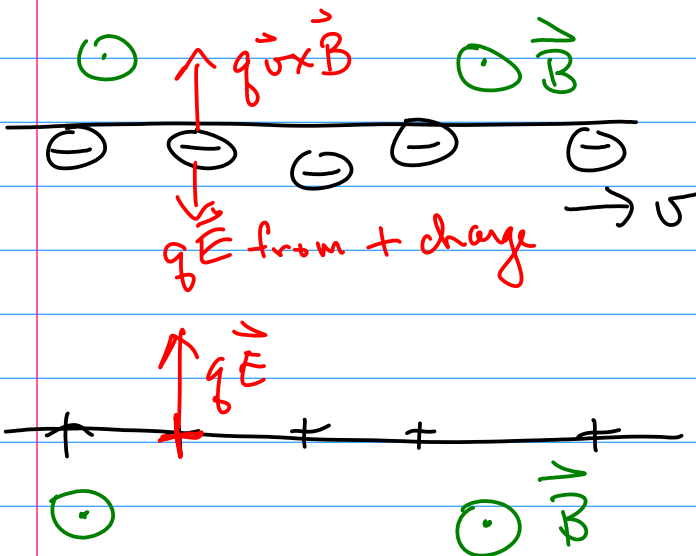
$\sum \rightarrow \int \Rightarrow$ Stokes theorem $\oint \vec{\nabla} \times \vec{F} \cdot d\vec{a} = \oint \vec{F} \cdot d\vec{r}$

sum inside bndry boundary integral

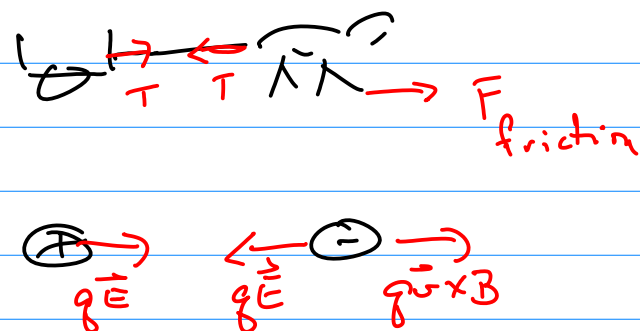
Fundamental th. cal says sum of df's from $x=a$ to $x=b$ is the difference in $f(b)-f(a)$, that is the values of the function at the boundary.
 For curls the sum is over the interior of an area and the result is a sum (a line integral) over the boundary.

InkSurvey question from Friday

What is the net force on a positive charge?



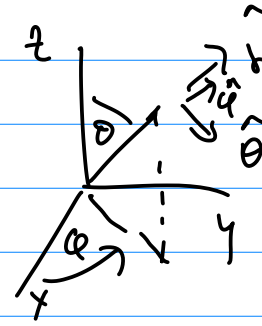
This is like the horse pulling the cart.



Muddiest points:

(1) How was the Lorentz force determined?

By measuring forces on current carrying wires.



(2) Cross product in spherical coords.

$$\hat{\theta} \times \hat{\phi} = \hat{r} \quad \hat{\phi} \times \hat{r} = \hat{\theta}$$

(3) Interpretation of curl on the surface of water.

Put a paddle wheel horizontally just under the water surface so it generates a vortex.

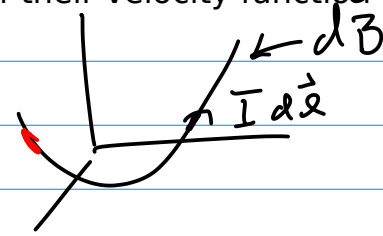
Pine needles just above will move in a circle. The curl of their velocity function will be non-zero.

(4) Force of wire on itself due to the B it generates.

$I d\vec{\ell}'$ generates $d\vec{B}$ at $I d\vec{\ell} \Rightarrow$ force

$I d\vec{\ell}$ generates $d\vec{B}$ at $I d\vec{\ell}' \Rightarrow$ opposite force

The net force on wire = 0



(5) What's the point of the curl?

We will use it to model magnetic fields from currents.

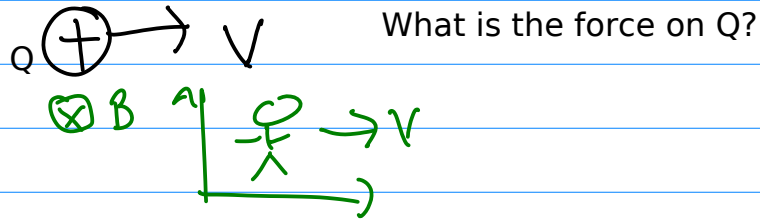
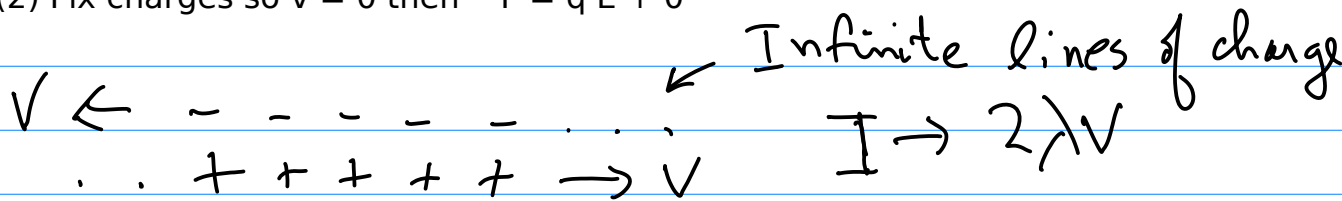
(6) So much material. How do I study for the next exam?

I will talk about what will be on the exam.

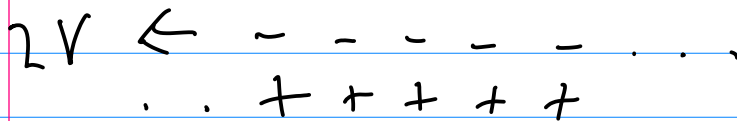
(7) Relativity and electric and magnetic fields.

See below

(2) Fix charges so $v = 0$ then $F = qE + 0$



Go to a reference frame moving to the right at speed V



What is the force on Q?

There is NO $q\vec{v} \times \vec{B}$ since $v = 0$

$$\vec{F} = q\vec{E} + q\underbrace{\vec{v} \times \vec{B}}_0$$

since $v = 0$ so $E \neq 0$

Moving charge density is greater due to length contraction so the negative charge density is greater than the positive thus attracting Q as expected.

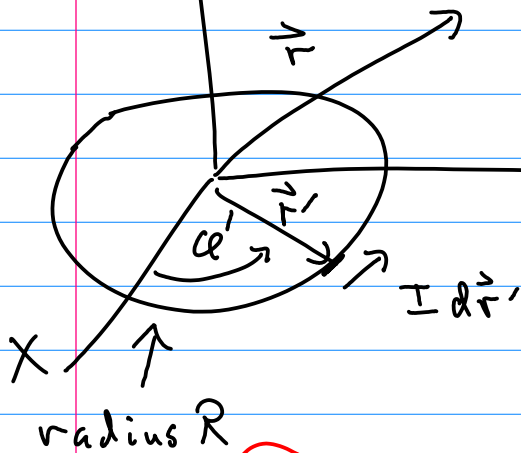
We will continue with a mathematical analysis once we know B from an infinite current moving along a line.

What have we covered?

Calculate B given currents

Law of Biot & Savart

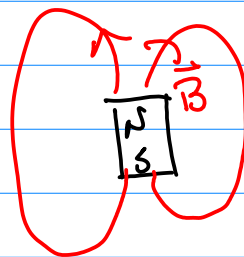
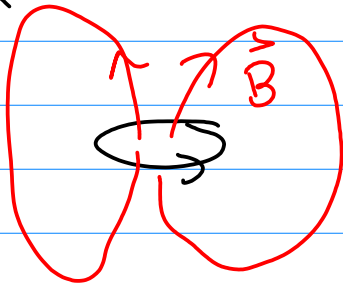
$$\vec{B}(\vec{r}) = \int d\vec{B} = \frac{\mu_0}{4\pi} \int \frac{I d\vec{r}' \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$



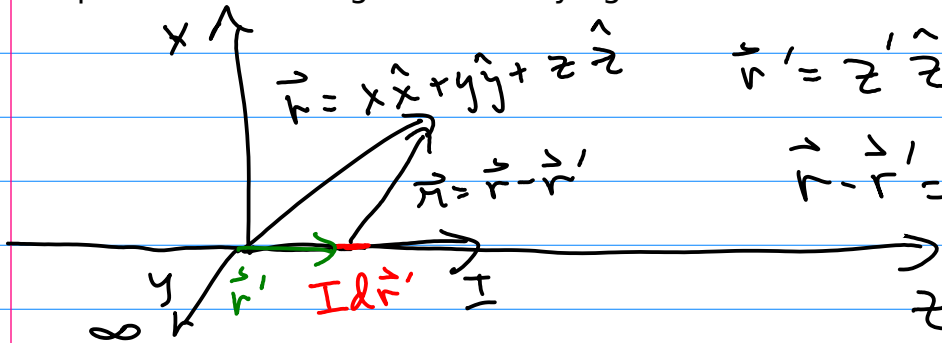
$$\vec{r} = x \hat{x} + y \hat{y} + z \hat{z}$$

$$d\vec{r}' = R d\phi' (-\sin\phi' \hat{x} + \cos\phi' \hat{y})$$

$$\vec{r}' = R \cos\phi' \hat{x} + R \sin\phi' \hat{y}$$



Example: infinite straight wire carrying constant current



$$\vec{r} = x \hat{x} + y \hat{y} + z \hat{z}$$

$$\vec{r}' = z' \hat{z} \quad d\vec{r}' = dz' \hat{z}$$

$$\vec{r} - \vec{r}' = x \hat{x} + y \hat{y} + (z - z') \hat{z}$$

$$|\vec{r} - \vec{r}'| = \sqrt{x^2 + y^2 + (z - z')^2}$$

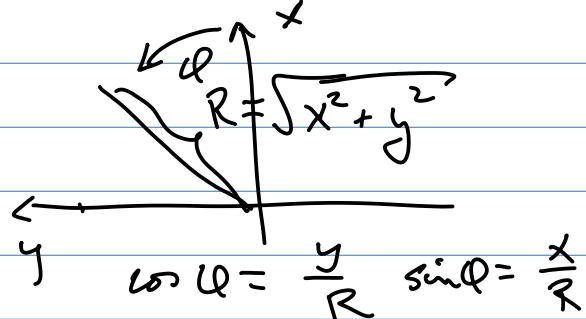
$$\vec{B} = \frac{\mu_0}{4\pi} \int_{-\infty}^{\infty} \frac{I d\vec{r}' \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \cdot \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} = \frac{x \hat{x} + y \hat{y} + (z - z') \hat{z}}{(x^2 + y^2 + (z - z')^2)^{3/2}}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 0 & 0 & dz' \\ \frac{x}{(\quad)^{3/2}} & \frac{y}{(\quad)^{3/2}} & \frac{z - z'}{(\quad)^{3/2}} \end{vmatrix}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int \left[\hat{x} \frac{(-dz' y)}{()^{3/2}} + \hat{y} \frac{dz' x}{()^{3/2}} \right]$$

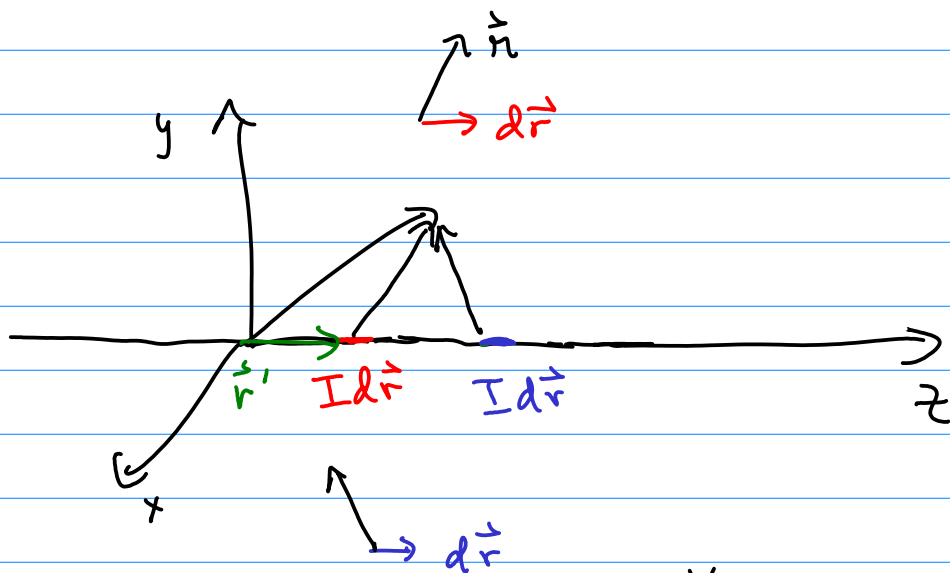
$$\vec{B} = \frac{\mu_0 I \hat{x}}{4\pi} \int_{-\infty}^{\infty} \frac{-dz' y}{(x^2 + y^2 + (z-z')^2)^{3/2}} + \frac{\mu_0 I \hat{y}}{4\pi} \int_{-\infty}^{\infty} \frac{dz' x}{(x^2 + y^2 + (z-z')^2)^{3/2}}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \left(-\frac{2y}{x^2 + y^2} \hat{x} + \frac{2x}{x^2 + y^2} \hat{y} \right)$$

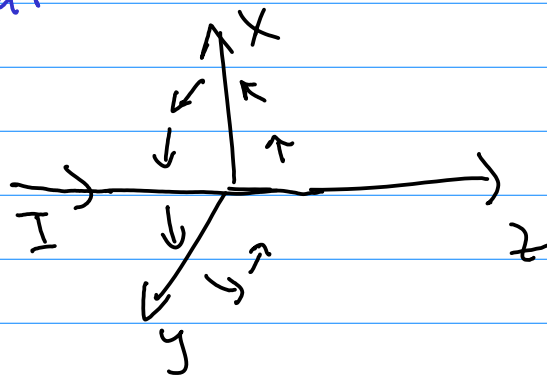


$$\vec{B} = \frac{\mu_0}{2\pi} \left(\frac{1}{R} \sin \phi \hat{x} - \frac{1}{R} \cos \phi \hat{y} \right)$$

$$\vec{B} = \frac{\mu_0}{2\pi R} \hat{\phi}$$



$$\vec{B} = \frac{\mu_0 I}{2\pi r} \hat{\phi}$$



What are we going to cover?

Helmholtz Theorem says we need $\vec{\nabla} \cdot$ & $\vec{\nabla} \times$ vector function to uniquely determine it.

General result

$$\vec{B}(x, y, z) = \int d\vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dx' dy' dz'$$

What is $\vec{\nabla} \cdot \vec{B}$?

$$\vec{\nabla} \cdot \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dx' dy' dz'$$

$$= \frac{\mu_0}{4\pi} \int \vec{\nabla} \cdot \left[\frac{\vec{J}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \right] dx' dy' dz'$$

$$\vec{\nabla} \cdot \left(\frac{\vec{J} \times \hat{r}}{r^2} \right) = \frac{\hat{r}}{r^2} \cdot (\vec{\nabla} \times \vec{J}) - \vec{J} \cdot \left(\vec{\nabla} \times \frac{\hat{r}}{r^2} \right)$$

Questions?

$$\vec{\nabla} \times \vec{J} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ J_x(x', y', z') & J_y(x', y', z') & J_z(x', y', z') \end{vmatrix} = 0$$

← No x, y, z dependence

$$\nabla \times \vec{J} = \vec{0}$$