

LAPLACE TRANSFORMS - SECOND-ORDER LINEAR EQUATIONS (REVISITED) - FORCED MASS-SPRING SYSTEMS

1. Calculate the Laplace transform of  $f_1(t) = \sinh(at)$  and  $f_2(t) = \cosh(at)$ ,  $a \in \mathbb{R}$ .

**Hint:** You may want to refer to the previous homework assignment for the definitions of  $\sinh(x)$  and  $\cosh(x)$  or you might find it more efficient to note that  $-i \sin(ix) = \sinh(x)$  and  $\cos(ix) = \cosh(x)$  and repeat the calculations we did in class to find  $\mathcal{L}\{\cos(kt)\}$  and  $\mathcal{L}\{\sin(kt)\}$ , which will find the transform of  $f_1$  and  $f_2$  simultaneously. Doing it this way should make the standard form for these transforms, [http://en.wikipedia.org/wiki/Laplace\\_transform#Table\\_of\\_selected\\_Laplace\\_transforms](http://en.wikipedia.org/wiki/Laplace_transform#Table_of_selected_Laplace_transforms), make more sense.

2. Using the definition of transform show the following relationships:

(a)  $\mathcal{L}\{e^{at}f(t)\} = F(s - a)$   
 (b)  $\mathcal{L}\{f(t - a)u_a(t)\} = e^{-as}F(s)$ ,  $a \geq 0$   
 (c)  $\mathcal{L}\{f(t)u_a(t)\} = e^{-as}\mathcal{L}\{f(t + a)\}$ ,  $a \geq 0$ .

3. Consider the following second-order linear ordinary differential equation with constant coefficients,

$$a \frac{d^2y}{dt^2} + b \frac{dy}{dt} + cy = \delta(t), \quad y(0) = 0, \quad y'(0) = 0. \quad (1)$$

Solve the IVP (1) for the following cases:

- (a)  $a = 1, b = -2, c = -3$   
 (b)  $a = 1, b = 4, c = 4$   
 (c)  $a = 1, b = -4, c = 13$   
 (d)  $a = 1, b = 0, c = 9$

4. Given the following forced simple harmonic oscillator.

$$2 \frac{d^2y}{dt^2} + 8y = 6 \cos(\omega t), \quad y(0) = 1, \quad y'(0) = -1. \quad (2)$$

- (a) Set  $\omega = 1$  and find the solution to the initial value problem.  
 (b) Set  $\omega = 2$  and find the solution to the initial value problem.  
 (c) Describe the differences in the long term behavior of the steady-state solution for each oscillator

5. Again we investigate the forced mass spring system given by,

$$m \frac{d^2y}{dt^2} + b \frac{dy}{dt} + ky = f(t), \quad m, b, k \in \mathbb{R}^+ \cup \{0\}. \quad (3)$$

- (a) Suppose we have that  $b = 0$ ,  $y(0) = \alpha$ ,  $y'(0) = \beta$  and  $f(t) = A\delta_T(t)$ , show that the solution to (3) subject to these constraints is given by,

$$y(t) = \alpha \cos(\omega t) + \frac{\beta}{\omega} \sin(\omega t) + \frac{A}{m\omega} u_T(t) \sin(\omega(t - T)), \quad (4)$$

where  $\omega^2 = \frac{k}{m}$ .

- (b) Suppose that we wish to hit the mass in such a way that after the impact the oscillations stop. Show that for this to occur we must choose,

$$A = \frac{\alpha m \omega}{\sin(\omega T)} \quad (5)$$

$$T = \frac{1}{\omega} \arctan\left(-\frac{\alpha \omega}{\beta}\right). \quad (6)$$