

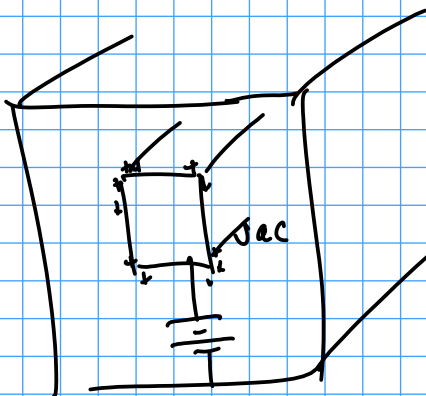
$$\vec{P} = \epsilon_0 \chi_e \vec{E}_{tot}$$

We want to find bound charge & then use all these charges to determine \vec{E} everywhere

σ_b $\hat{=}$ pt charge

$$\sigma_b = \vec{P} \cdot \hat{n} = P_z = \epsilon_0 \chi_e \frac{1}{\epsilon_0} E_{tot} = \sigma_b$$

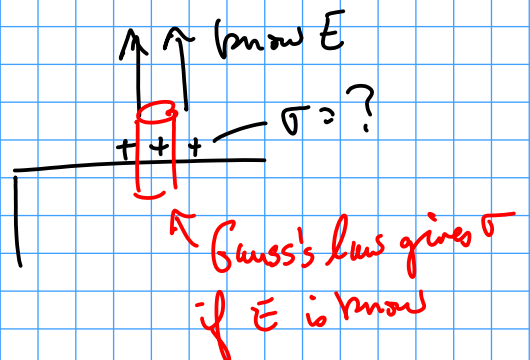
linear



Solved Laplace's eqn to get V

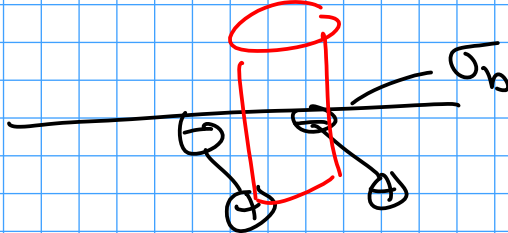
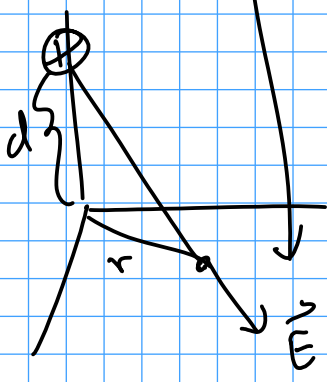
$$\vec{E} = -\vec{\nabla} V$$

to get σ



E_{pt}^{\perp}

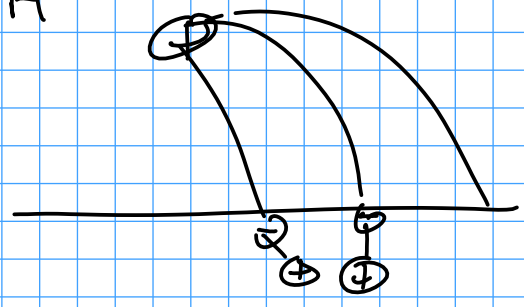
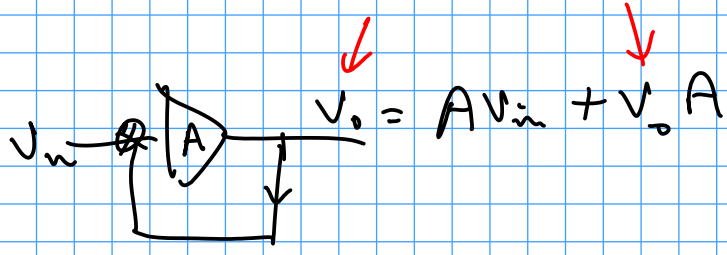
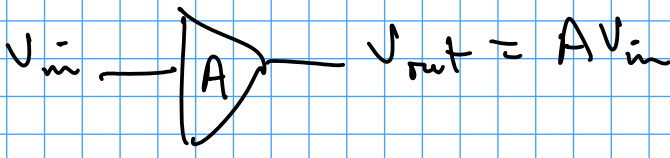
$$E_{tot}^{\perp} = E_{pt. charge}^{\perp} + E_{bound charge}^{\perp} = -\frac{1}{4\pi\epsilon_0} \frac{qd}{(r^2+d^2)^{3/2}} +$$



Gauss's Law $\Rightarrow E_{bound}^{\perp} = \frac{\sigma_b}{2\epsilon_0}$

$$E_{tot}^{\perp} = -\frac{1}{4\pi\epsilon_0} \frac{qd}{(r^2+d^2)^{3/2}} + \frac{\sigma_b}{2\epsilon_0}$$

$$\epsilon_0 \chi_e E_{tot}^{\perp} = \sigma_b = \epsilon_0 \chi_e \left\{ -\frac{1}{4\pi\epsilon_0} \frac{qd}{(r^2+d^2)^{3/2}} + \frac{\sigma_b}{2\epsilon_0} \right\}$$



Cons. charge

$$\vec{J} = \rho \vec{v} \quad \begin{matrix} \text{m/s} \\ \text{C} \\ \text{m}^3 \end{matrix}$$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

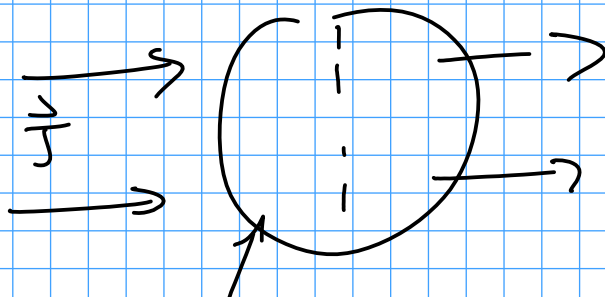
↑
dynamic

Static $\vec{\nabla} \cdot \vec{J} = 0$

no source of charge (\vec{J})

$$\begin{pmatrix} \vec{\nabla} \cdot \vec{B} = 0 \\ \vec{\nabla} \cdot \vec{E} = \rho / \epsilon_0 \end{pmatrix}$$

integral form! $\int \vec{\nabla} \cdot \vec{J} d\tau = \oint \vec{J} \cdot d\vec{a} = 0$



$$\int_{\text{left}} \vec{J} \cdot d\vec{a} + \int_{\text{right}} \vec{J} \cdot d\vec{a} = 0$$

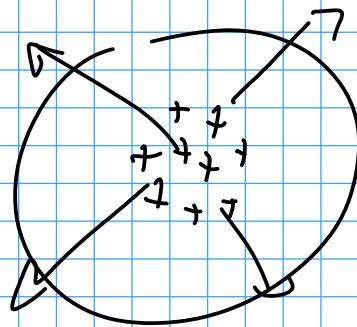
dyn

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

$$\oint \vec{J} \cdot d\vec{a} = -\frac{\partial}{\partial t} Q_{\text{enc}}$$

$$\oint \vec{J} \cdot d\vec{a} = -\frac{\partial}{\partial t} Q_{\text{enc}}$$

out of surface.



Ex: 1-D motion of cars on a freeway

$$-\frac{\partial p}{\partial t} = \nabla \cdot \mathbf{J} \xrightarrow{1-D} \frac{\partial(\lambda v)}{\partial x} = -\frac{\partial \lambda}{\partial t}$$

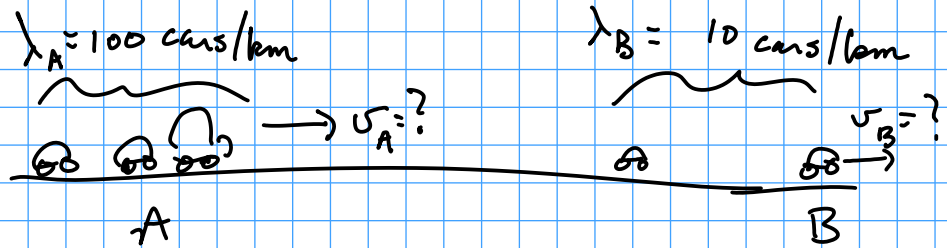
integral form multiply both sides by dx

$$\int \frac{\partial(\lambda v)}{\partial x} dx = -\frac{\partial}{\partial t} \int \lambda dx$$

Ex:

$$(\lambda v)_f - (\lambda v)_i = -\frac{\partial Q_{enc}}{\partial t}$$

$\lambda \left(\frac{C}{m} \right)$ or $\left(\frac{Cars}{km} \right)$



Steady state

$$(\lambda v)_B - (\lambda v)_A = 0$$

$$\lambda_B v_B = 10 \frac{cars}{km} v_B$$

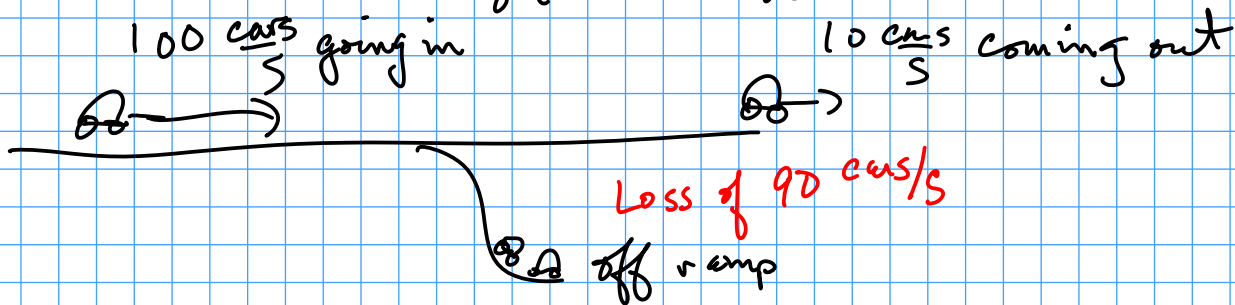
$$\lambda_A v_A = 100 \frac{cars}{km} v_A$$

$$10 v_B = 100 v_A$$

non-steady state: Let cars move at $1 \frac{km}{s}$ at both A & B

$$\lambda_A v_A - \lambda_B v_B = (100 - 10) \frac{1 km}{s} = 90 \frac{cars km}{s} = 90 \frac{cars}{s}$$

$$= -\frac{\partial}{\partial t} \int \lambda dx = -\frac{\partial}{\partial t} [\text{cars between A \& B}]$$



Cons in QM.

$$\rho \rightarrow \psi^* \psi \frac{p \text{ vol}}{\text{vol}}$$

$$\vec{J} = \frac{\hbar}{m} \frac{1}{2i} (\psi^* \vec{\nabla} \psi - \psi \vec{\nabla} \psi^*) \leftarrow$$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t} = -\frac{\partial (\psi^* \psi)}{\partial t}$$

Conservation prob

Plane waves

$$\psi = \psi_0 e^{i(kx - \omega t)}$$

$$\nabla \psi = \psi_0 i k e^{i(kx - \omega t)}$$

$$J = \frac{\hbar}{m} \frac{1}{2i} (\psi^* \psi i k + \psi \psi^* i k) = \frac{\hbar}{m} k \psi^* \psi = \frac{\hbar}{m} \frac{m \omega}{\hbar} \psi^* \psi$$

$$p = \hbar k = m v_g$$

$$k = \frac{m \omega}{\hbar}$$

$$J = \psi^* \psi v_g = \rho v_g$$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

$$\rho = \psi^* \psi$$
$$J = \rho v_g$$