

recall

$$\begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \lambda \begin{pmatrix} x \\ y \end{pmatrix}$$

has 2 Eigenvalue / Eigenvector pairs

$$6, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{and} \quad 4, \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\lambda_1 \vec{q}_1 \quad \lambda_2 \vec{q}_2$$

notice that  $(\vec{q}_1, \vec{q}_2) = 0$

These vectors are orthogonal.

Let's normalize them

$$\vec{q}_1 \rightarrow \frac{1}{\sqrt{2}} (1, 1)$$

$$\vec{q}_2 \rightarrow \frac{1}{\sqrt{2}} (1, -1)$$

$$\text{So } (\vec{q}_1, \vec{q}_2) = (\vec{q}_2, \vec{q}_1) = 0$$

$$(\vec{q}_1, \vec{q}_1) = (\vec{q}_2, \vec{q}_2) = 1$$

Together, these eigenvectors form an orthogonal matrix

$$Q = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$Q^T Q = Q Q^T = I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Similarly, the eigenvalues form a diagonal matrix

$$\Lambda = \begin{pmatrix} 6 & 0 \\ 0 & 4 \end{pmatrix}$$

↑  
Lambda

Amazing result

$$Q \Lambda Q^T = \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix}$$

Since  $Q^T Q = I$

$$\Lambda = Q^T \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} Q$$

This is called the diagonalization of the original matrix.

Diagonalization of matrices can be thought of as a coordinate transformation in which linear systems become simple

NB today we treat  
only symmetric matrices  
many (most) matrices that  
arise in physics are symm.

Nonsymmetric problems  
are much harder. Later

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Also NB if  $A\vec{x} = \lambda\vec{x}$

then  $A(\alpha\vec{x}) = \lambda(\alpha\vec{x})$

So  $\Sigma$ -vectors are not

unique

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$$A \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} A^{-1}$$

consider  $A\vec{x} = \vec{y}$  

suppose  $Q$  is an orthogonal matrix, then


$$Q^T Q = I \Rightarrow$$

$$A Q^T Q \vec{x} = \vec{y} \quad \text{insert } I.$$

$$Q A Q^T Q \vec{x} = Q \vec{y} \quad \text{multiply by } Q$$
$$\begin{matrix} [ & ] \\ \vec{x} & \vec{y} \end{matrix}$$

$$Q A Q^T \vec{x} = \vec{y}$$

if  $Q A Q^T = \Lambda$  then

  $\Rightarrow \Lambda \vec{x} = \vec{y}$

$$= \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

immediately we have

$$x_1^r = \frac{1}{\lambda_1} y_1^r$$

$$\vdots$$
$$x_i^r = \frac{1}{\lambda_i} y_i^r$$

The original solution  $\vec{x}$  is related to  $\vec{x}^r$  by

$$Q \vec{x} = \vec{x}^r$$

$$\Rightarrow \vec{x} = Q^T \vec{x}^r = Q^T \Lambda^{-1} \vec{y}^r$$

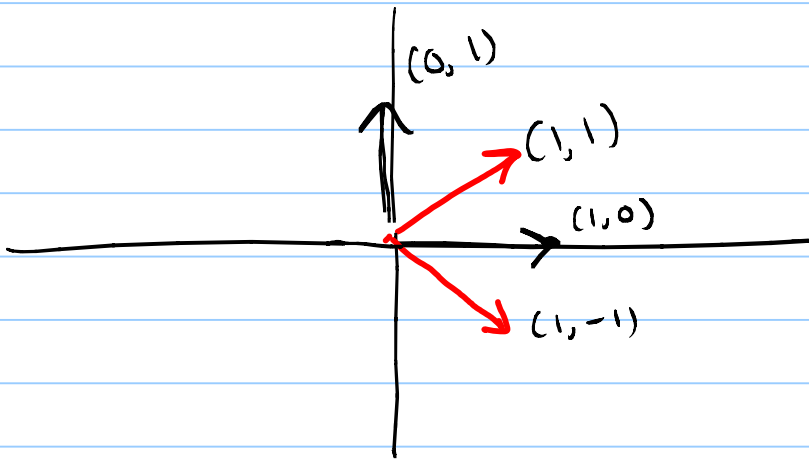
$$\boxed{\vec{x} = Q^T \Lambda^{-1} Q \vec{y}}$$

$$\vec{x} = A^{-1} \vec{y}$$

Key idea: in the new coordinates the problem becomes easy

$$\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

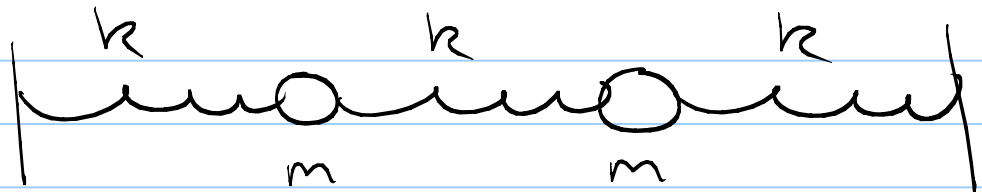
$$\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$



# Important example

diagonalizing coupled oscillator problem leads to uncoupled oscillators!

Example



can show

$$\begin{aligned} \ddot{X}_1 &= -2\omega_0^2 X_1 + \omega_0^2 X_2 \\ \ddot{X}_2 &= -2\omega_0^2 X_2 + \omega_0^2 X_1 \end{aligned}$$

Seek solutions:  $X_1 = Ae^{i\omega t}$   
 $X_2 = Be^{i\omega t}$



Plug into  $\star$

$$\underbrace{\begin{pmatrix} 2\omega_0^2 & -\omega_0^2 \\ -\omega_0^2 & 2\omega_0^2 \end{pmatrix}}_{\text{matrix}} \underbrace{\begin{pmatrix} A \\ B \end{pmatrix}}_{\text{vect}} = \omega^2 \underbrace{\begin{pmatrix} A \\ B \end{pmatrix}}_{\text{vector}}$$

scalar

$$K \vec{u} = \omega^2 \vec{u}$$
$$\vec{u} = \begin{pmatrix} A \\ B \end{pmatrix} \quad K = \begin{pmatrix} 2\omega_0^2 & -\omega_0^2 \\ -\omega_0^2 & 2\omega_0^2 \end{pmatrix}$$

Lets solve this problem

characteristic polynomial =

$$\text{Det}(A - \omega^2 I)$$

$$\text{Det} \begin{pmatrix} 2\omega_0^2 - \omega^2 & -\omega_0^2 \\ -\omega_0^2 & 2\omega_0^2 - \omega^2 \end{pmatrix}$$

$$= (2\omega_0^2 - \omega^2)^2 - \omega_0^4 = 0$$

$$\Rightarrow 2\omega_0^2 - \omega^2 = \pm \omega_0^2$$

$$\Rightarrow \omega_{\pm}^2 = 2\omega_0^2 \mp \omega_0^2$$

$$\boxed{\begin{matrix} \omega_+^2 = 3\omega_0^2 \\ \omega_-^2 = \omega_0^2 \end{matrix}} \quad \text{\textit{\epsilon}-values}$$

plug these into

$$\underbrace{\begin{pmatrix} 2\omega_0^2 & -\omega_0^2 \\ -\omega_0^2 & 2\omega_0^2 \end{pmatrix}}_{\text{matrix}} \underbrace{\begin{pmatrix} A \\ B \end{pmatrix}}_{\text{vect}} = \underbrace{\omega^2}_{\text{scalar}} \underbrace{\begin{pmatrix} A \\ B \end{pmatrix}}_{\text{vector}}$$

$$2\omega_0^2 A - \omega_0^2 B = 3\omega_0^2 A$$

$$-\omega_0^2 A + 2\omega_0^2 B = \omega_0^2 B$$

Any motion of the 2 coupled masses can be written as a linear comp. of the  $\xi$ -vectors

$$X(t) = \alpha \xi_1(t) + \beta \xi_2(t)$$

$\xi$ -vectors

$$3\omega_0^2 \Rightarrow -\omega_0^2 B = \omega_0^2 A$$

$$\Rightarrow B = -A$$

$$\text{eigen vector} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\omega_0^2 \Rightarrow -\omega_0^2 A = -\omega_0^2 B$$

$$\Rightarrow A = B$$

$$\text{eigen vector} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

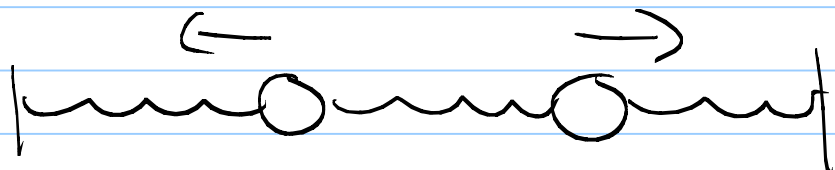
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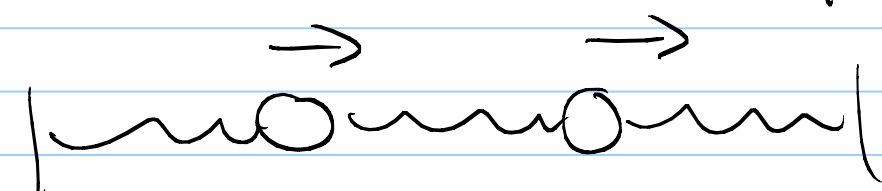
$$3\omega_0^2, \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\omega_0^2 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

fast motion

slow motion

$3\omega_0^2$  |  | out of phase

$\omega_0^2$  |  | in phase

original coupled eqn's.

$$K \vec{u} = \omega^2 \vec{u}$$

$$\vec{u} = \begin{pmatrix} A \\ B \end{pmatrix} \quad K = \begin{pmatrix} 2\omega_0^2 & -\omega_0^2 \\ -\omega_0^2 & 2\omega_0^2 \end{pmatrix}$$

$$K = \Phi \Lambda \Phi^T$$

$$\Rightarrow \Phi \Lambda \Phi^T \vec{u} = \omega^2 \vec{u}$$

$$\Rightarrow \Lambda \underbrace{\Phi^T \vec{u}}_{\vec{u}^r} = \omega^2 \underbrace{\Phi^T \vec{u}}_{\vec{u}^r}$$

$$\boxed{\Lambda \vec{u}^r = \omega^2 \vec{u}^r}$$

The equations are now uncoupled since  $\Lambda$  is diagonal

$$\Lambda \vec{u} = \omega^2 \vec{u}$$

$$\begin{bmatrix} 3\omega_0^2 & 0 \\ 0 & \omega_0^2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \omega^2 \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$3\omega_0^2 u_1 = \omega^2 u_1$$

$$\omega_0^2 u_2 = \omega^2 u_2$$

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Example of an important application.

Suppose

$$A = Q \Lambda Q^T$$

$$A^2 = A \cdot A = (Q \Lambda Q^T)(Q \Lambda Q^T)$$

$$\underbrace{Q^T Q}_{= I}$$

$$= Q \Lambda^2 Q^T$$

$$\dots$$
$$A^2 = Q \Lambda^2 Q^T$$

e.g. since  $e^x = 1 + x + \frac{x^2}{2} + \dots$

we guess that

$$e^A = I + A + \frac{A^2}{2} + \dots$$
$$= Q \Lambda^0 Q^T + Q \Lambda^1 Q^T + Q \frac{\Lambda^2}{2} Q^T + \dots$$
$$= Q \left[ \Lambda^0 + \Lambda^1 + \frac{\Lambda^2}{2} + \dots \right] Q^T$$

In QM this arises in  
the time-evolution operator  
for Schrödinger's equation