

### Contracted notation

If Kleinman's symmetry is valid, each of the three matrices are symmetric:

$$\begin{bmatrix} \cdot & & & & & \\ & \cdot & & & & \\ & & \cdot & & & \\ & & & \cdot & & \\ & & & & \cdot & \\ & & & & & \cdot \end{bmatrix} \quad \begin{bmatrix} \cdot & & & & & \\ & \cdot & & & & \\ & & \cdot & & & \\ & & & \cdot & & \\ & & & & \cdot & \\ & & & & & \cdot \end{bmatrix} \quad \begin{bmatrix} \cdot & & & & & \\ & \cdot & & & & \\ & & \cdot & & & \\ & & & \cdot & & \\ & & & & \cdot & \\ & & & & & \cdot \end{bmatrix} = 18 \text{ elements.}$$

contract second pair of indices to 1:

$$\begin{array}{rcccccc} jk & 11 & 22 & 33 & 23,32 & 31,13 & 12,21 \\ & \downarrow & & & & & \\ l & 1 & 2 & 3 & 4 & 5 & 6 \end{array}$$

$$\rightarrow d_{ijl} = \begin{bmatrix} \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{bmatrix} \quad \text{now just one matrix.}$$

not all are independent: can permute indices  $\rightarrow$  max 10 independent.  
- see slide

Crystal symmetry further reduces the # of independent and non-zero matrix elements.

32 possible crystal point groups

21 are non-centrosymmetric  $\rightarrow$  no second-order response.

w/ inversion symmetry,  $\chi^{(2)} = 0$

SHG example

$$P(t) = \chi^{(2)} E(t)^2$$

$$E(t) = E_0 \cos \omega t$$

$$\text{if } E(t) \rightarrow -E(t)$$

$$P(t) \rightarrow -P(t) \quad \text{with inversion symmetry.}$$

$$\text{but } P(t) = \chi^{(2)} (-E(t))^2 \stackrel{?}{=} -P(t)$$

$$\therefore \chi^{(2)} = 0$$

similar arguments for crystal symmetries

Effective  $d$ :

actual orientation of fields is restricted by phase matching:

$$\text{for } \omega_3 = \omega_1 + \omega_2$$

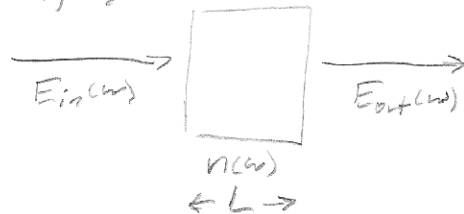
$$k_3 = k_1 + k_2 \quad \text{or} \quad \Delta k = k_1 + k_2 - k_3 = 0$$

within this restriction  $\rightarrow$  case of angles.

- value of  $d$  determines best choice.
- we'll return to this when we treat phase matching.

Time vs. frequency domain

Linear response:



$$E_{out}(\omega) = E_{in}(\omega) e^{ik_0 n(\omega) L}$$

linear propagation is easiest to describe in freq. space.

- linear systems:  $H(\omega) =$  transfer fun, freq. response

$$F_{out}(\omega) = H(\omega) F_{in}(\omega)$$

$$F_{out}(t) = \mathcal{F}^{-1} \{ H(\omega) F_{in}(\omega) \}$$

$$= h(t) \otimes f_{in}(t)$$

where  $= \int_{-\infty}^{\infty} h(\tau) f_{in}(t-\tau) d\tau$  is convolution. convolution theorem

if input is  $f_{in}(t) = \delta(t)$  (impulse)

$$F_{out}(t) = \int_{-\infty}^{\infty} h(\tau) \delta(t-\tau) d\tau = h(t)$$

$\therefore h(t) = \mathcal{F}^{-1} \{ H(\omega) \}$  is impulse response.

At a microscopic level,  $p(t)$  is the induced dipole when  $E(t)$  is in, and  $P(t) = N_A p(t)$  is the collective response.

When we solve for  $\chi^{(1)} = N_A P/E$ , our method gives  $\chi^{(1)}(\omega)$

recall steps:  $E(t) = E_0 e^{-i\omega t} + c.c.$

$$X^{(1)}(t) = X_0^{(1)} e^{-i\omega t} + c.c.$$

$$X_0^{(1)} = -(\epsilon/m) E_0 / D(\omega)$$

$$\chi^{(1)}(\omega) = N_A e^2 / m / D(\omega)$$

So what is the impulse response? For a range of input freqs:

$$P''(\omega) = X''(\omega) E(\omega)$$

Alternative method: take FT of 2<sup>nd</sup> order eqn.

note that  $\mathcal{F}\left\{\frac{d}{dt}f(t)\right\} = -i\omega F(\omega)$   
 $\rightarrow$  eqn for  $X''(\omega)$  with  $E(\omega)$  driving

Now in time domain

$$P''(t) = \mathcal{F}^{-1}\left\{X''(\omega) E(\omega)\right\}$$

Recognise  $X''(\omega)$  as a transfer function.

let  $R''(t) \equiv \mathcal{F}^{-1}\left\{X''(\omega)\right\} \equiv$  impulse response

$$\text{Then } P''(t) = \int_{-\infty}^{\infty} R''(\tau) E(t-\tau) d\tau = R'' \otimes E$$

(normally have  $\frac{1}{2\pi}$  in front, this is absorbed into def'n of  $R$ )

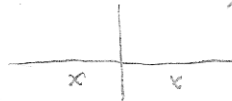
What is the nature of  $R''(t)$ ?

- causality requires  $R''(t) = 0$  for  $t < 0$
- expect? damped SLD response to a kick:



$$\text{- Proof: } \mathcal{F}^{-1}\left\{X''(\omega)\right\} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{N(e^{i\tau/\tau_0})}{\omega^2 - \omega_0^2 - 2i\omega} e^{-i\omega t} d\omega$$

requires contour integration: poles are off real axis:



for  $t < 0$  close on upper half  $\rightarrow \square$

for  $t > 0$  close lower.

Time dependent NL response.

in NL case, we have multiple input fields.

- can arrive at different times.

$$e.g. P^{(2)}(t) = \int_0^\infty dt_1 \int_0^\infty dt_2 R^{(2)}(t_1, t_2) E(t-t_1) E(t-t_2)$$

$R^{(2)} = 0$  for either  $t_1 < 0$  or  $t_2 < 0$  (causality)

put  $E(\omega)$  in

$$\rightarrow \int_{-\infty}^{\infty} \frac{d\omega_1}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega_2}{2\pi} \int_0^\infty dt_1 \int_0^\infty dt_2 R^{(2)}(t_1, t_2) E(\omega_1) e^{-i\omega_1(t-t_1)} \times E(\omega_2) e^{-i\omega_2(t-t_2)}$$

$$= \int_{-\infty}^{\infty} \frac{d\omega_1}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega_2}{2\pi} \chi^{(2)}(\omega_3; \omega_1, \omega_2) E(\omega_1) E(\omega_2) e^{-i\omega_3 t}$$

where  $\omega_3 = \omega_1 + \omega_2$

$$\chi^{(2)}(\omega_3; \omega_1, \omega_2) = \int_0^\infty dt_1 \int_0^\infty dt_2 R^{(2)}(t_1, t_2) e^{i(\omega_1 t_1 + \omega_2 t_2)}$$

similar for  $\chi^{(3)}$

Note that if response is assumed to be instantaneous, then

is no dispersion in  $\chi$

In some important systems, response is delayed.

- e.g. Raman:

