

In order to receive full credit, **SHOW ALL YOUR WORK**. Full credit will be given only if all reasoning and work is provided. When applicable, please enclose your final answers in boxes.

1. (10 Points) True/False and Short Response

(a) Mark each statement True or False.

i. If \mathbf{A} is an invertible matrix then $\mathbf{A}^{-1}\mathbf{x} = \mathbf{0}$ has a non-trivial solution.

False

ii. Any set of n vectors from \mathbb{R}^m , such that $n > m$, forms a linearly dependent set.

True

iii. If $\mathbf{A}_{m \times n}$ has a pivot in every column then its columns span \mathbb{R}^m .

False

iv. If $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$ then $\det(\mathbf{A} + \mathbf{B}) = \det(\mathbf{A}) + \det(\mathbf{B})$

False

v. The determinant of an elementary matrix corresponding to a row-interchange is 1.

False

(b) Please respond to **one** of the following questions and justify your position:i. Suppose \mathbf{A} is a 4×3 matrix with the property that $\mathbf{Ax} = \mathbf{0}$ has a unique solution. What can you say about the reduced echelon form of \mathbf{A} ? What can you conclude about the system $\mathbf{Ax} = \mathbf{b}$ when \mathbf{b} is a vector in \mathbb{R}^4 ?ii. Suppose \mathbf{A} is a 3×3 matrix and \mathbf{y} is a vector in \mathbb{R}^3 such that the equation $\mathbf{Ax} = \mathbf{y}$ does not have a solution. Does there exist a vector \mathbf{z} in \mathbb{R}^3 such that the equation $\mathbf{Ax} = \mathbf{z}$ has a unique solution?

ii) If $\mathbf{Ax} = \mathbf{y}$ has no soln $\Rightarrow \mathbf{A}$ is not invertible \Rightarrow True vers
 $\Rightarrow \mathbf{Ax} = \mathbf{z}$ has no soln or non unique soln

i) $\mathbf{Ax} = \mathbf{0} \Rightarrow$ 3 pivots $\Rightarrow \mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \mathbf{Ax} = \mathbf{b}$ may have a unique soln or no soln.
 only $\mathbf{x} = \mathbf{0}$

2. (10 Points) Quickies:

$$\left[\begin{array}{cc|c} 1 & 3 & 2 \\ 3 & h & k \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 3 & 2 \\ 0 & h-3 & k-2 \end{array} \right]$$

(a) Let $\mathbf{A} = \begin{bmatrix} 1 & 3 \\ 3 & h \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} 2 \\ k \end{bmatrix}$. Find all values of h and k for which the system $\mathbf{Ax} = \mathbf{b}$ is:

i. Consistent with a unique solution.

$$h \neq 3, k \in \mathbb{R}$$

ii. Consistent with infinity-many solutions.

$$h = 3, k = 2$$

iii. Inconsistent.

$$h = 3, k \neq 2$$

(b) Invert the following matrices,

$$\mathbf{A}_1 = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{A}_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}, \quad \mathbf{A}_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}, \quad \mathbf{A}_4 = \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix}.$$

$$\mathbf{A}_1^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{A}_2^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}, \quad \mathbf{A}_3^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}, \quad \mathbf{A}_4^{-1} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$$

(c) ~~Solve the following linear system and~~ describe the geometry of the general solution set, ~~to~~

$$3x_1 - 9x_2 + 6x_3 = 0 \quad (1)$$

$$-x_1 + 3x_2 - 2x_3 = 0 \quad (2)$$

$$\left[\begin{array}{ccc|c} 3 & -9 & 6 & 0 \\ -1 & 3 & -2 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 3 & -9 & 6 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \text{ These are the same plane!}$$

3. (10 Points) Proofs:

(a) If \mathbf{A} is invertible prove that $\mathbf{B} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T$ exists and that $\mathbf{B} = \mathbf{A}^{-1}$.

$$\mathbf{A}^{-1} \text{ exists} \Rightarrow (\mathbf{A}^T)^{-1} \text{ exists} \Rightarrow (\mathbf{A}^T \mathbf{A})^{-1} \text{ exists} \Rightarrow \mathbf{B} \text{ exists}$$
$$\mathbf{B} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T = \mathbf{A}^{-1} (\mathbf{A}^T)^{-1} \mathbf{A}^T = \mathbf{A}^{-1} \checkmark$$

(b) Prove that $\mathbf{A} \mathbf{A}^T$ is a symmetric matrix.

$$(\mathbf{A} \mathbf{A}^T)^T = \mathbf{A}^T \mathbf{A} = \mathbf{A} \mathbf{A}^T \checkmark$$

(c) Prove that $(\mathbf{A} + \mathbf{B})^T = \mathbf{A}^T + \mathbf{B}^T$

$$[(\mathbf{A} + \mathbf{B})^T]_{ij} = [\mathbf{A} + \mathbf{B}]_{ji} = a_{ji} + b_{ji}$$
$$[\mathbf{A}^T + \mathbf{B}^T]_{ij} = a_{ji} + b_{ji} \Rightarrow (\mathbf{A} + \mathbf{B})^T = \mathbf{A}^T + \mathbf{B}^T$$

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4. (10 Points) Given,

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -3 \\ 2 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -3 \\ 9 \\ -6 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 5 \\ -7 \\ h \end{bmatrix}.$$

(a) For what values of h is \mathbf{v}_3 in the $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$?

(b) For what values of h are the vectors $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ a linearly dependent?

$$a) \left[\begin{array}{ccc|c} 1 & -3 & 5 & 0 \\ -3 & 9 & -7 & 0 \\ 2 & -6 & h & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & -3 & 5 & 0 \\ 0 & 0 & 8 & 0 \\ 0 & 0 & h-10 & 0 \end{array} \right]$$

$\mathbf{v}_3 \notin \text{span}\{\vec{v}_1, \vec{v}_2\}$ for any h !

b) \vec{v}_1, \vec{v}_2 are lin. dep. $\Rightarrow \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is always lin. dep.

5. (10 Points) Given,

$$A = \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 2 & 3 & 4 \end{bmatrix}, \quad L = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2/3 & -1/2 & 1 \end{bmatrix}.$$

(a) Find U associated with the LU decomposition of A .

Hint: Don't forget what information is encoded into L !

$$A = \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 2 & 3 & 4 \end{bmatrix} \xrightarrow{R_3 = R_3 - \frac{2}{3}R_1} \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 0 & -1 & -2/3 \end{bmatrix} \xrightarrow{R_2 = R_2 + \frac{1}{2}R_1} \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 0 & 0 & -1/6 \end{bmatrix} = U$$

$3 - \frac{2}{3} \cdot 6 = 1$
 $4 - \frac{2}{3} \cdot 7 = \frac{12}{3} - \frac{14}{3} = -\frac{2}{3}$
 $-\frac{2}{3} + \frac{1}{2} = -\frac{4+3}{6}$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2/3 & -1/2 & 1 \end{bmatrix} \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 0 & 0 & -1/6 \end{bmatrix} = \begin{bmatrix} 3 & 6 & 7 \\ 0 & 2 & 1 \\ 2 & 3 & 4 \end{bmatrix}$$

$$\frac{2}{3} \cdot 6 - \frac{1}{2} \cdot 2 = 4 - 1 = 3, \quad \frac{2}{3} \cdot 7 - \frac{1}{2} \cdot 1 = \frac{14}{3} - \frac{1}{2} = \frac{28}{6} - \frac{3}{6} = \frac{25}{6}$$

(b) Using the LU decomposition solve $Ax = b$ where $b = \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$.

$$LUx = b \Leftrightarrow Ly = b, \quad Ux = y$$

$$\begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & | & 2 \\ 2/3 & -1/2 & 1 & | & -1 \end{bmatrix} \Rightarrow \begin{matrix} x_1 = 0 \\ x_2 = 2 \\ x_3 = 0 \end{matrix} \Rightarrow \begin{bmatrix} 3 & 6 & 7 & | & 0 \\ 0 & 2 & 1 & | & 2 \\ 0 & 0 & -1/6 & | & 0 \end{bmatrix} \Rightarrow \begin{matrix} x_1 = -2 \\ x_2 = 1 \\ x_3 = 0 \end{matrix} \Rightarrow \vec{x} = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$$

(c) Calculate the determinant of A .

Hint: Properties of determinants should make this calculation very straightforward.

$$\det(A) = \det(LU) = \det(L) \det(U) = 1 \cdot 3 \cdot 2 \cdot \frac{1}{6} = 1$$

1:02

6. (Extra Credit 1) True/False,

(a) If the equation $Ax = b$ is inconsistent, then b is not in the set spanned by the columns of A .

True.

(b) If x is a non-trivial solution to $Ax = 0$, then every entry in x is non-zero.

False

(c) If x and y are linearly independent and if $\{x, y, z\}$ is a linearly dependent set then z is in $\text{Span}\{x, y\}$

True

(d) If A and B are diagonal matrices then $AB=BA$.

True

(e) $\det(A^T) = -\det(A)$

False

7. (Extra Credit 2) Invert the matrix from problem 5. Check your work with the appropriate matrix multiplication.

See HW # 34.