

## Delta functions and point sources

We've already seen indications that point charges behave a bit wonky, even though they do seem to exist experimentally. I'm afraid this is going to get a bit worse before it gets better.

Let's look at Gauss's law again. If we take the divergence of an  $E$ -field, we should recover the charge density that produced that field:

$$\nabla \cdot \vec{E} = \rho / \epsilon_0$$

What happens if we take the divergence of the field made by a point charge at the origin?

$$\nabla \cdot \left( \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2} \right) = ? \quad \text{Apply the divergence operator in spherical coordinates}$$

$$= \frac{1}{r^2} \frac{d}{dr} \left( r^2 \cdot \frac{q}{4\pi\epsilon_0 r^2} \right)$$

$$= \frac{1}{r^2} \frac{d}{dr} \left( \frac{q}{4\pi\epsilon_0} \right) = 0 ?$$

Well, according to that, the divergence of something like  $\frac{\hat{r}}{r^2}$  is zero everywhere. Thus, so must  $\rho$  be zero everywhere. But that can't be right. So what's the catch?

The catch is that the operator  $\frac{1}{r^2} \frac{d}{dr} (r^2)$  isn't super well-defined at the origin. All we can conclude from the above is that  $\nabla \cdot \vec{E}$  is zero everywhere but the origin.

To deal with the origin, let's take a look at delta functions first.

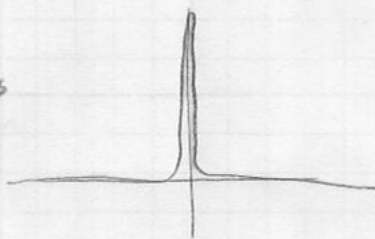
A delta function is used to represent a finite amount of stuff compressed into an essentially zero-dimensional domain. In one dimension, a delta function  $\delta(x)$  is defined as the thingy that satisfies these two properties:

$\delta(x)$  is a delta function if:

1)  $\delta(x) = 0 \quad \forall x \text{ except } x=0, \text{ where } \delta \text{ is undefined}$

2)  $\int \delta(x-a) f(x) dx = f(a)$  if  $a$  is in the domain of integration, or zero otherwise

Basically, its a very sharply peaked function that, when present in an integral, plucks out the value of another function at one point.



So how do we represent  $\rho(\vec{r})$  for a point charge of size  $q$  in 3D? How about a delta function?

$$\rho(\vec{r}) = q\delta^3(\vec{r})$$

(Or, if the point is at  $\vec{r}'$  instead of the origin,  $q\delta^3(\vec{r}-\vec{r}')$ )

With that in mind, since  $\nabla \cdot \vec{E} = \rho/\epsilon_0$ , it should be the case that

$$\nabla \cdot \left( \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2} \right) = q\delta^3(\vec{r})$$

And therefore  $\nabla \cdot \frac{\hat{r}}{r^2} = 4\pi\delta^3(\vec{r})$

Is that true?

Well, its true if

$$1) \quad \nabla \cdot \frac{\hat{r}}{r^2} = 0 \quad \text{everywhere but the origin.}$$

And we established that.

$$2) \quad \int (\nabla \cdot \frac{\hat{r}}{r^2}) d^3x = 4\pi \quad \text{for a domain including the origin.}$$

Let's integrate  $\nabla \cdot \frac{\hat{r}}{r^2}$  over a sphere of radius  $R$ .

Just doing that as a volume integral is tricky since the integrand is undefined at the origin, so dodge the bad part by using the divergence theorem:

$$\begin{aligned} \int (\nabla \cdot \frac{\hat{r}}{r^2}) d^3x &= \oint \frac{\hat{r}}{r^2} \cdot d\vec{A} \\ &= \oint \frac{\hat{r}}{r^2} \cdot r^2 \sin\theta d\theta d\phi \hat{r} \\ &= \oint \sin\theta d\theta d\phi \quad (\text{over a sphere}) \\ &= 4\pi \end{aligned}$$

So it checks out.  $\nabla \cdot \frac{\hat{r}}{r^2} = 4\pi \delta^3(r)$ , and thus

$$\nabla \cdot \left( \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2} \right) = q \delta^3(r) \frac{1}{\epsilon_0} = \rho / \epsilon_0$$