

Reading: Today: 12.1

The morrow: 12.2

What makes a vector a vector?  
It has magnitude / direction.  
or 3-components.

But you need more.

1) How does it rotate?

Rotations can be written as  
a similarity transformation

$$\vec{x}' = A \vec{x}$$

↑  
rotation matrix

$|A| = 1$  for proper rotations

$|A| = -1$  for improper rotations

↑  
rotation + odd #  
of reflections  
(parity transformation)

For a true vector, improper rotations  
flip its sign, but for some "vectors", that's  
not true.

Say ang. momentum :  $\vec{L} = \vec{r} \times \vec{p}$

Something else is time reversal.

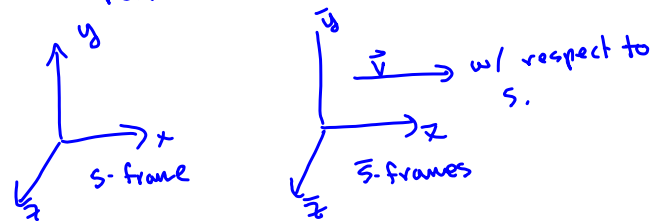
$\vec{x}$  even under time reversal  
(doesn't change for a given  
value of  $t$ .)

velocity  $\rightarrow \vec{v}$ ; odd under time reversal  
(flips sign if you go  
backward in  $t$ ).

$$\vec{v} = \frac{d\vec{x}}{dt}; t \rightarrow -t \text{ flips sign.}$$

Thing	Let's make a List		ref. frame.
	Rank {How it rotates}	space inv. parity	
$\vec{x}(\vec{r})$	1	odd	even
$\vec{v}$	1	odd	odd
$\vec{p}$	1	odd	odd
$\vec{L}$	1	even	odd
$\vec{F}$	1	odd	even
$\vec{r} \times \vec{F}$	1	even	even
Kin. Ene	0	even	even
Pot. E	0	even	even
$\rho$	0	even	even
$\vec{j}$	1	odd	odd
$\vec{E}$	1	odd	even
$\vec{B}$			
$\vec{H}$	1	even	odd
$\vec{E}$			
$\vec{S}$	1	odd	odd
$\vec{T}$	2	even	even
$\vec{D}$	1	odd	even

The question is, how do these things transform when changing ref. frames.



The speed of light in any reference frame is the same constant,  $c$ .  
 {i.e. for all observers}

Consequence is

$$\left. \begin{aligned} \bar{x} &= \gamma(x - vt) + x_0 \\ \bar{y} &= y + y_0 \\ \bar{z} &= z + z_0 \\ \bar{t} &= \gamma\left(t - \frac{v}{c^2}x\right) + t_0 \end{aligned} \right\} \begin{aligned} x &= \gamma(\bar{x} + v\bar{t}) - x_0 \\ y &= \bar{y} - y_0 \\ z &= \bar{z} - z_0 \\ t &= \gamma\left(\bar{t} + \frac{v}{c^2}\bar{x}\right) - t_0 \end{aligned}$$

$v$  is really  $v_x$ , and it has a sign!

For simplicity, at  $t=0$ , set  $\bar{t}=0$   $\begin{matrix} x = \bar{x} \\ y = \bar{y} \\ z = \bar{z} \end{matrix}$   
 $\rightarrow x_0, y_0, z_0, t_0 = 0$

## What are the consequences?

Simultaneity?

Let's say in frame  $S$  that something happens at  $t=0$  at  $x=\pm a$

two things.

↓

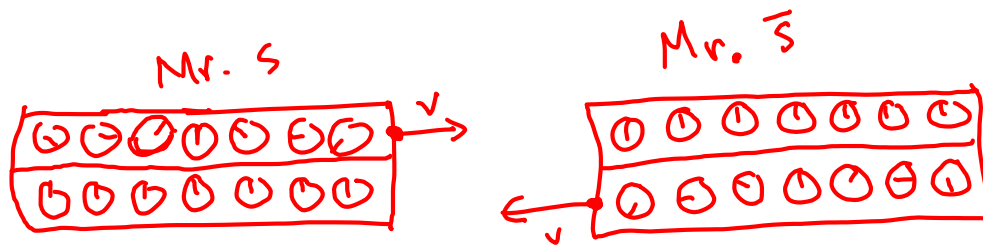
something

Question: what does Mr.  $\bar{S}$  say?

$$\text{He says } \bar{t}_1 = \frac{\gamma v}{c^2} a \quad \{x = -a\}$$

$$\bar{t}_2 = -\frac{\gamma v}{c^2} a \quad \{x = a\}$$

Both Mr.  $S$ , and Mr.  $\bar{S}$  set up synchronized clocks in their frames. What does that look like?



As an exercise for the reader show for a single clock in  $\bar{S}$ ,  $\bar{x} = \text{const}$   
 $\Delta t = \gamma \Delta \bar{t} \rightarrow \Delta \bar{t} = \frac{1}{\gamma} \Delta t \leftarrow \text{time dilation}$

Take  $\Delta \bar{x}$  but w/  $\Delta t = 0$

$$\rightarrow \Delta \bar{x} = \gamma \Delta x \leftarrow \text{length contraction}$$

## 4 vectors

$$x^{\mu} = (ct, x, y, z) \leftarrow \text{contravariant vector}$$

$$x_{\mu} = (-ct, x, y, z) \leftarrow \text{covariant vector.}$$

Contravariant vectors transform like  
{when going from  $s \rightarrow \bar{s}$ }

$$\bar{x}^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}$$

$\beta = v/c$

$$\Lambda^{\mu}_{\nu} = \begin{pmatrix} \gamma - \gamma\beta & 0 & 0 & 0 \\ 0 & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

any contravariant vector  
not just  $x$

For the reader,

show  $\Lambda^{\mu}_{\nu} = \frac{\partial \bar{x}^{\mu}}{\partial x^{\nu}}$  using the Lorentz eqns from before.

A contravariant vector is one which transforms like  $\bar{v}^{\mu} = \frac{\partial \bar{x}^{\mu}}{\partial x^{\nu}} v^{\nu}$

A covariant vector is one which transforms like  $\bar{v}_{\mu} = \frac{\partial x^{\mu}}{\partial \bar{x}^{\nu}} v_{\nu}$

How do I change

$$x^{\mu} \rightarrow x_{\mu}$$

or vice versa

Enter the metric  $g_{\mu\nu} = g^{\mu\nu}$

For special relativity (flat space)

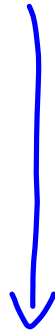
$$g_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

$$g_{\mu\nu} a^{\mu} = a_{\nu}$$



# Dot products

$$a_\mu b^\mu = \underline{\underline{\text{scalar}}}$$



↑  
Same in all  
reference frames.

$$g_{\mu\nu} a^\nu b^\mu \quad \{ \text{Generalization} \}$$

How to transform  
tensors.

$$\bar{T}^{\mu\nu} = \frac{\partial \bar{x}^{\mu}}{\partial x^{\gamma}} \frac{\partial \bar{x}^{\nu}}{\partial x^{\alpha}} T^{\gamma\alpha}$$